

Layered and Object-Based Game Semantics

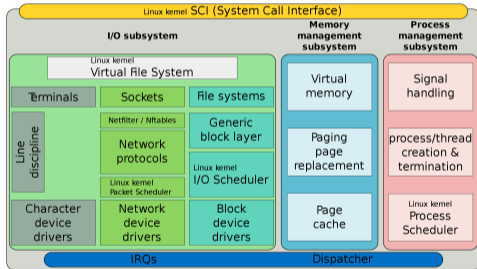
Arthur Oliveira Vale¹ Paul-André Melliès² Zhong Shao¹ Jérémie Koenig¹
Leo Stefanescu³

¹Yale University, USA

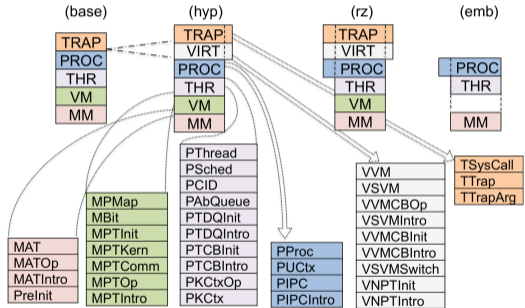
²CNRS and Université de Paris

³MPI-SWS, Germany

Layered Systems



https://commons.wikimedia.org/wiki/File:Simplified_Structure_of_the_Linux_Kernel.svg

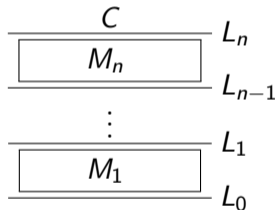


Certified Abstraction Layers

► **Layer:**



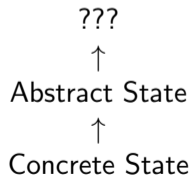
► **Layering:**



► **Certified Implementation:**

$$L_1 \vdash M : L_2$$

► **Encapsulation:**



Modeling State: Global vs Local State

Global State:

- ▶ C Memory Model
- ▶ ML Reference Types
- ▶ Haskell State Monads
- ▶ Algebraic Effects (Global)
- ⋮

Local State:

- ▶ Algebraic Effects (Local)
- ▶ Object-Based Semantics
- ⋮

Object-Based Semantics

Lisp and Symbolic Computation, 9, 7-76 (1996)

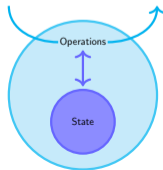
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Global State Considered Unnecessary: An Introduction to Object-Based Semantics

UDAY S. REDDY

reddy@cs.uiuc.edu

Department of Computer Science, University of Illinois at Urbana-Champaign, Urbana, IL.



Object-Based Semantics

Lisp and Symbolic Computation, 9, 7-76 (1996)

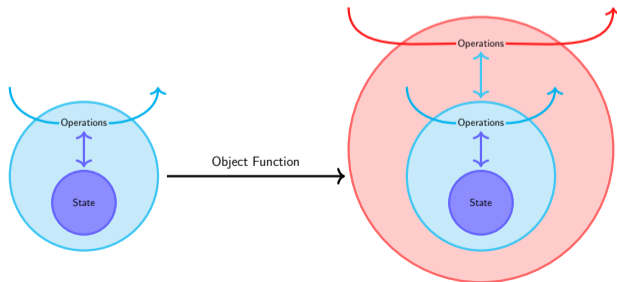
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Object-Based Semantics and Certified Abstraction Layers

Object Type \approx Layer Signature

Object \approx Layer Specification

Object Function \approx Layer Implementation

??? \approx Certified Layer

How to build compositional semantic models for certifying large heterogenous systems?

Our Contributions

- ▶ A novel model of Certified Abstraction Layers.
 - ▶ No explicit state
 - ▶ Rooted in linear logic
 - ▶ Clarifies some aspects of the abstract semantics of CAL
 - ▶ Supports an operational account as a game semantics model
 - ▶ Supports a denotational account as a domain-theoretic model
- ▶ Generalized notion of layer interface that faithfully encapsulates state
- ▶ An extension to handle non-determinism in layer interfaces
- ▶ An extension to support concurrency

Outline

Introduction

Layer Signatures: E

Implementations: $M : \dagger E \multimap F$

Layer Interfaces: $L = (E, V_E)$

Certified Layer Implementations: $L_1 \vdash M : L_2$

Non-Deterministic Layer Specifications: $L = (E, \mathcal{V}_E)$

Concurrent Layers: $L = (E, R, V_E)$

Conclusion

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Layer Signatures

DEFINITION

An **effect signature** consists of

- ▶ A set E of **operations**
- ▶ A set $\text{ar}(e)$ to each operation e called the **arity** of e

EXAMPLE

- ▶ $\text{Var} := \{\text{get} : 1 \rightarrow \mathbb{N}, \text{set} : \mathbb{N} \rightarrow 1\}$:

Operations $\text{Var} = \{\text{get}, \text{set}(n) \mid n \in \mathbb{N}\}$

Arities ▶ $\text{ar}(\text{get}) = \mathbb{N}$

▶ $\text{ar}(\text{set}(n)) = 1 \cong \{\text{ok}\}$

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Arities ▶ $\text{ar}(\text{get}) = \mathbb{N}$

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State-Based Layer Specifications

Var := {get : $1 \rightarrow \mathbb{N}$, set : $\mathbb{N} \rightarrow 1$ }

State: $n, m \in S_{\text{Var}} := \mathbb{N}$

Initial State: 0

Transitions: $n \xrightarrow{\text{get}.n} n$
 $n \xrightarrow{\text{set}(m).\text{ok}} m$

FAI := {fai : $1 \rightarrow \mathbb{N}$ }

State: $n \in S_{\text{FAI}} := \mathbb{N}$

Initial State: 0

Transitions: $n \xrightarrow{\text{fai}.n} n + 1$

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Bounded Queue

Signature

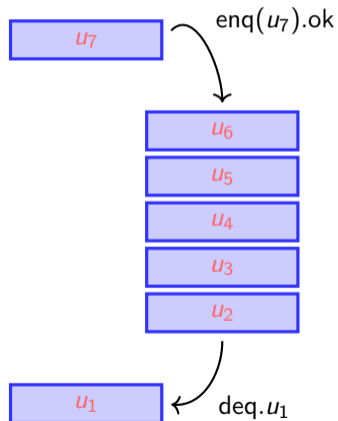
$$E_{\text{bq}} := \{\text{enq} : \mathbb{U} \rightarrow 1, \text{deq} : 1 \rightarrow \mathbb{U}\}$$

States $S_{\text{bq}} = \mathbb{U}^*$

Initial State ϵ

- Transitions
- ▶ $|\vec{q}| < N \Rightarrow \vec{q} \xrightarrow{\text{enq}(v).\text{ok}} \vec{q}v$
 - ▶ $\vec{q} = v\vec{q}' \Rightarrow \vec{q} \xrightarrow{\text{deq}.v} \vec{q}'$

Queue Semantics:



Bounded Queue

Signature

$$E_{\text{bq}} := \{\text{enq} : \mathbb{U} \rightarrow 1, \text{deq} : 1 \rightarrow \mathbb{U}\}$$

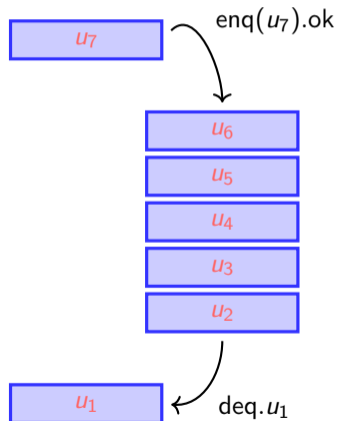
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Queue Semantics:



Ring Buffer

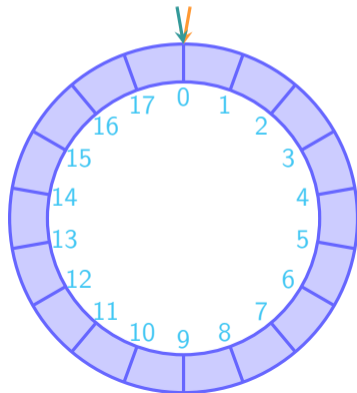
Signature:

$$E_{\text{bq}} := \{\text{set} : \mathbb{N} \times \mathbb{U} \rightarrow \mathbb{1}, \text{get} : \mathbb{N} \rightarrow \mathbb{U}\} \\ \cup \{\text{fai}_1 : \mathbb{1} \rightarrow \mathbb{N}, \text{fai}_2 : \mathbb{1} \rightarrow \mathbb{N}\}$$

State: $S_{\text{rb}} := \mathbb{U}^{\mathbb{N}} \times \mathbb{N} \times \mathbb{N}$

Initial State: $(\emptyset, 0, 0)$

Initial State:



Ring Buffer

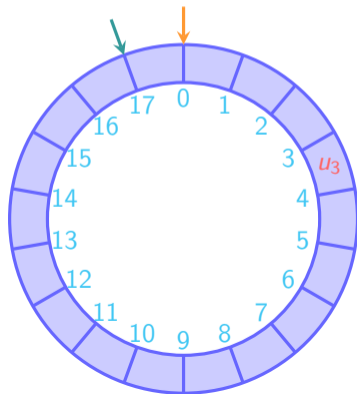
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$$(\emptyset, 0, 17) \xrightarrow{\text{set}(3, u_3).\text{ok}} (\{3 \mapsto u_3\}, 0, 17)$$

State: $S_{\text{rb}} := \mathbb{U}^{\mathbb{N}} \times \mathbb{N} \times \mathbb{N}$

Initial State: $(\emptyset, 0, 0)$

set Semantics:



Ring Buffer

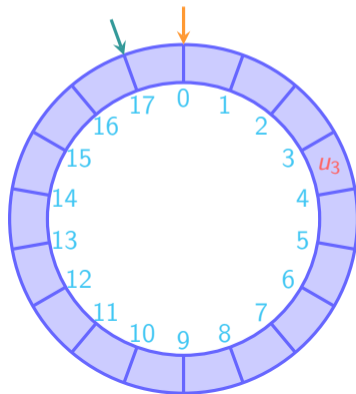
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get Semantics:



Ring Buffer

Signature:

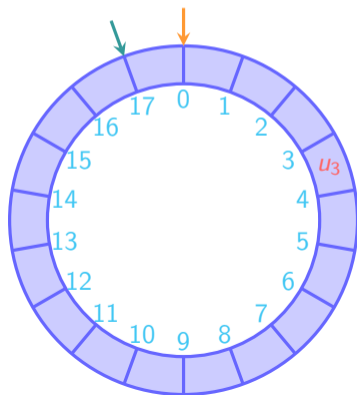
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get Semantics:

$$(\{3 \mapsto u_3\}, 0, 17) \xrightarrow{\text{get}(0), u_3}$$



Ring Buffer

Signature:

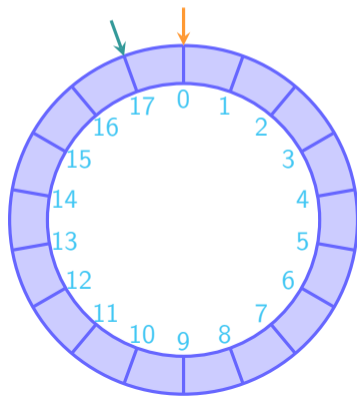
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Initial State: $(\emptyset, 0, 0)$

fai Semantics:

$$(\emptyset, 0, 17) \xrightarrow{\text{fai}_1.0} (\emptyset, 1, 17)$$



Ring Buffer

Signature:

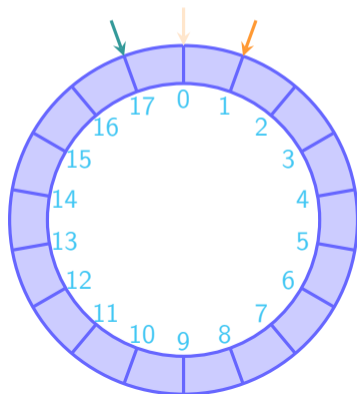
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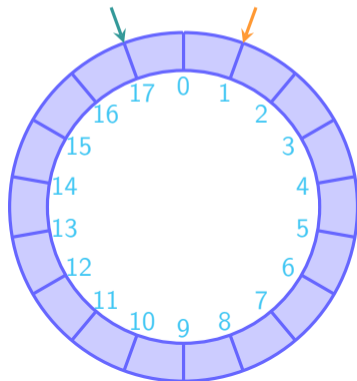
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Initial State: $(\emptyset, 0, 0)$

fai Semantics:

$$(\emptyset, 1, 17) \xrightarrow{\text{fai}_2.17} (\emptyset, 1, 0)$$



Ring Buffer

Signature:

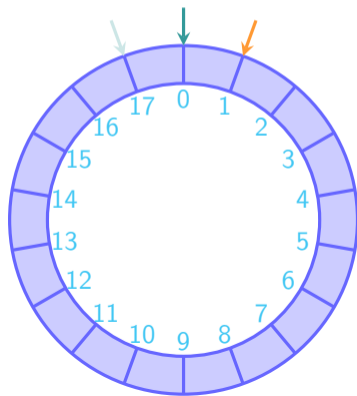
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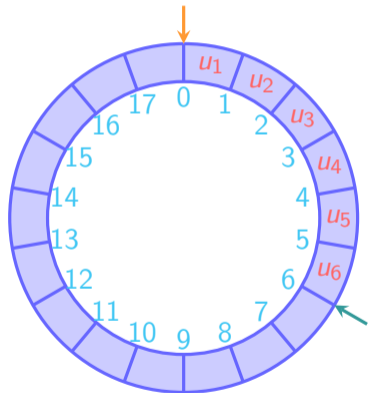
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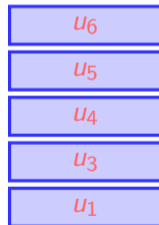
Implementing a Bounded Queue using a Ring Buffer



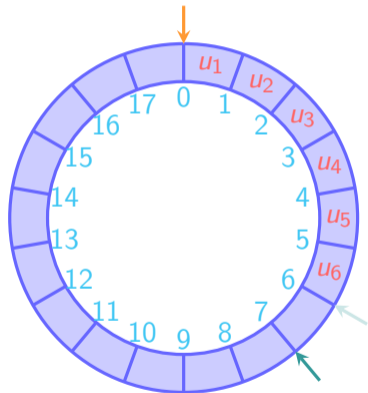
M

```
enq(u) {  
  i ← fai2();  
  set(i, u);  
  return ok  
}  
deq() {  
  i ← fai1();  
  get(i)  
}
```

enq(u_7)



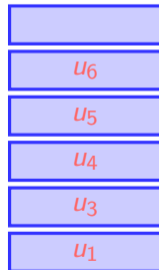
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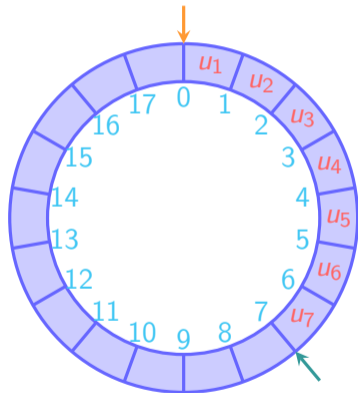
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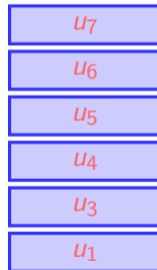
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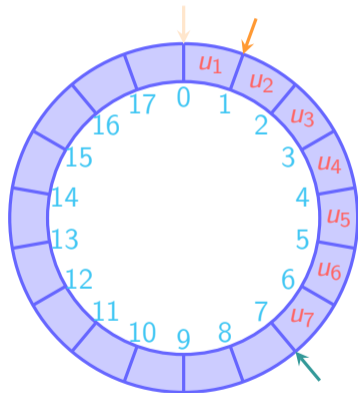
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enq(u_7).ok



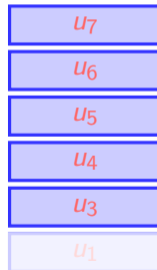
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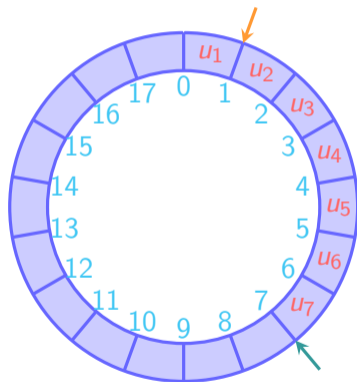
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  get(i)  
}
```

deq



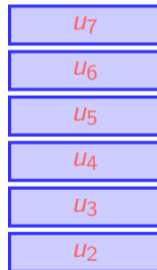
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  get(i)  
}
```

deq. u_1



Outline

Introduction

Layer Signatures: E

Implementations: $M : \dagger E \multimap F$

Layer Interfaces: $L = (E, V_E)$

Certified Layer Implementations: $L_1 \vdash M : L_2$

Non-Deterministic Layer Specifications: $L = (E, \mathcal{V}_E)$

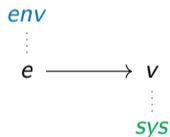
Concurrent Layers: $L = (E, R, V_E)$

Conclusion

Layer Signatures and Interactions

EXAMPLE

Every effect signature E has an associated game, which for every $e \in E$ and $v \in \text{ar}(e)$, has a play:



$$E_{\text{rb}} := \{\text{set} : \mathbb{N} \times \mathbb{U} \rightarrow \mathbf{1}, \text{get} : \mathbb{N} \rightarrow \mathbb{U}\} \\ \cup \{\text{fai}_1 : \mathbf{1} \rightarrow \mathbb{N}, \text{fai}_2 : \mathbf{1} \rightarrow \mathbb{N}\}$$

$$\text{set}(i, u) \longrightarrow \text{ok}$$

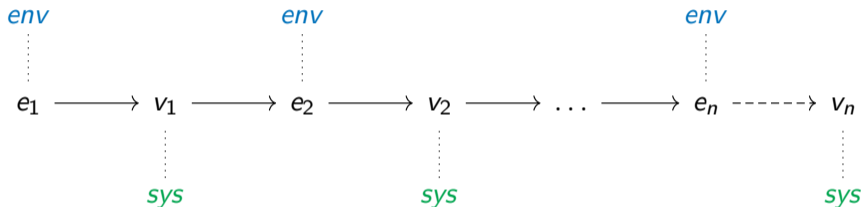
$$\text{get}(i) \longrightarrow u$$

$$\text{fai}_1 \longrightarrow v$$

$$\text{fai}_2 \longrightarrow v$$

The Replay Modality $\dagger E$

The game $\dagger E$ consists of plays:



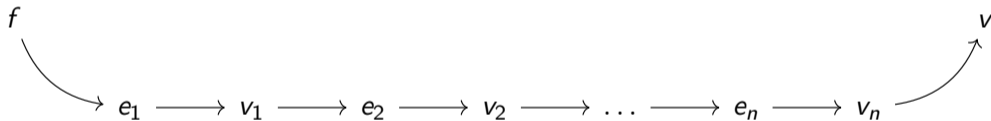
EXAMPLE

A linear logic modality $\dagger E_{rb}$ describes plays as sequences of E_{rb} interactions:

- ▶ $fai_1 \longrightarrow 0 \longrightarrow fai_1 \longrightarrow 1 \longrightarrow fai_1 \longrightarrow 2$
- ▶ $fai_1 \longrightarrow 7 \longrightarrow get(3) \longrightarrow u_3 \longrightarrow set(2, u_2) \longrightarrow ok \longrightarrow fai_2 \longrightarrow 13$

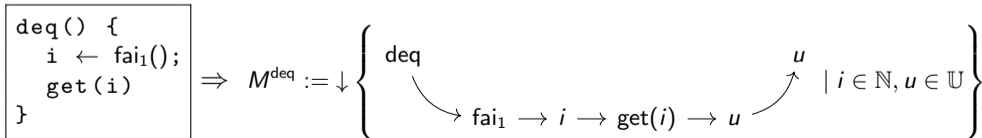
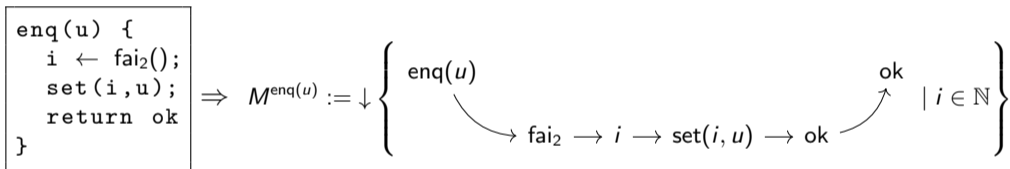
Implementation Plays: $\dagger E \multimap F$

Plays of $\dagger E \multimap F$ are of the form



Implementations: Example

$$M := \left(\bigcup_{u \in \mathbb{U}} M^{\text{enq}(u)} \right) \cup M^{\text{deq}}$$



Regular Extensions

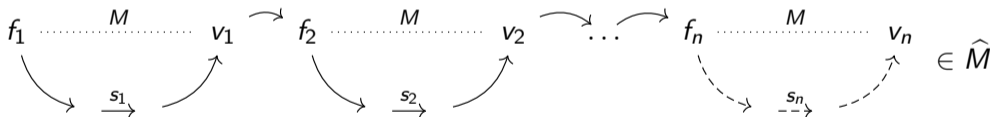
From an implementation:

$$M : \dagger E \multimap F$$

We build its regular extension:

$$\hat{M} : \dagger E \multimap \dagger F$$

by



In general, approximately:

$$\hat{M} \approx M^*$$

With local states implementations are stateless!

Implementations as Strategies

An implementation $M : E \rightarrow F$ is a **deterministic strategy** of type $\dagger E \multimap F$.

That is, M is a set of plays that is:

- ▶ **non-empty**,
- ▶ **prefix-closed**,
- ▶ **deterministic**

The Structure of the Replay Modality

The replay modality $\dagger-$ is a Comonad:

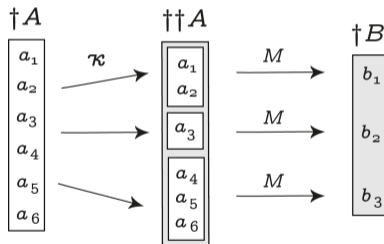
$$\epsilon_A : \dagger A \multimap A$$

$$\kappa_A : \dagger A \multimap \dagger\dagger A$$

The regular extension is just the Kleisli morphism:

$$M : \dagger A \multimap B$$

$$\dagger A \xrightarrow{\widehat{M}} \dagger B = \dagger A \xrightarrow{\kappa_A} \dagger\dagger A \xrightarrow{\dagger M} \dagger B$$



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Conclusion

Layer Specifications from State Transition Systems

How to get rid of state-based specifications?

Counter := {get : 1 → ℕ, inc : 1 → 1}

State: $n \in S_{\text{Counter}} := \mathbb{N}$

Initial State: 0

Transitions: $n \xrightarrow{\text{get}.n} n$
 $n \xrightarrow{\text{inc.ok}} n + 1$



Denote the observable behaviors at state q as:

$$(S, \rightarrow)\#q$$

$$(S_{\text{Counter}}, \rightarrow_{\text{Counter}})\#0 = \{\epsilon, \text{get} \cdot 0, \text{inc} \cdot \text{ok}, \text{get} \cdot 0 \cdot \text{get} \cdot 0, \text{inc} \cdot \text{ok} \cdot \text{get} \cdot 1, \\ \text{get} \cdot 0 \cdot \text{inc} \cdot \text{ok}, \text{inc} \cdot \text{ok} \cdot \text{inc} \cdot \text{ok}, \text{get} \cdot 0 \cdot \text{inc} \cdot \text{ok} \cdot \text{get} \cdot 1, \dots\}$$

Layer Specifications from State Transition Systems

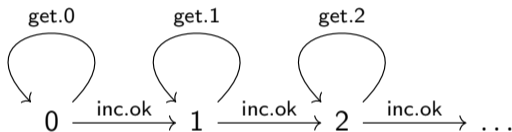
How to get rid of state-based specifications?

Counter := {get : 1 → ℕ, inc : 1 → 1}

State: $n \in S_{\text{Counter}} := \mathbb{N}$

Initial State: 0

Transitions: $n \xrightarrow{\text{get}.n} n$
 $n \xrightarrow{\text{inc.ok}} n + 1$



Denote the observable behaviors at state q as:

$$(S, \rightarrow)\#q$$

$$(S_{\text{Counter}}, \rightarrow_{\text{Counter}})\#0 = \{\epsilon, \text{get} \cdot 0, \text{inc} \cdot \text{ok}, \text{get} \cdot 0 \cdot \text{get} \cdot 0, \text{inc} \cdot \text{ok} \cdot \text{get} \cdot 1, \\ \text{get} \cdot 0 \cdot \text{inc} \cdot \text{ok}, \text{inc} \cdot \text{ok} \cdot \text{inc} \cdot \text{ok}, \text{get} \cdot 0 \cdot \text{inc} \cdot \text{ok} \cdot \text{get} \cdot 1, \dots\}$$

Layer Specifications from State Transition Systems

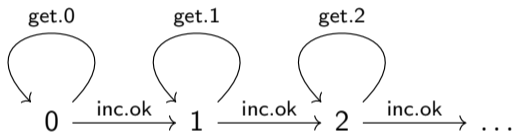
How to get rid of state-based specifications?

Counter := {get : 1 → ℕ, inc : 1 → 1}

State: $n \in S_{\text{Counter}} := \mathbb{N}$

Initial State: 0

Transitions: $n \xrightarrow{\text{get}.n} n$
 $n \xrightarrow{\text{inc.ok}} n + 1$



Denote the observable behaviors at state q as:

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Bounded Queue Specification: V_{bq}

EXAMPLE (BOUNDED QUEUE)

Signature $E_{\text{bq}} = \{\text{enq} : \mathbb{U} \rightarrow 1, \text{deq} : 1 \rightarrow \mathbb{U}\}$

States $S_{\text{bq}} = \mathbb{U}^*$

Initial State ϵ

Transitions

- ▶ $|\vec{q}| < N \Rightarrow \vec{q} \xrightarrow{\text{enq}(v).\text{ok}} \vec{q}v$
- ▶ $\vec{q} = v\vec{q}' \Rightarrow \vec{q} \xrightarrow{\text{deq}.v} \vec{q}'$

We can define a layer specification for E_{bq} as

$$V_{\text{bq}} := (S_{\text{bq}}, \rightarrow)\# \epsilon$$

Stateless Variable Specification: V_{Var}

EXAMPLE

V_{Var} is the set of plays s of $\dagger\text{Var}$ satisfying:



$$s = \quad \text{get} \longrightarrow v \longrightarrow \dots \quad \Rightarrow v = 0$$



$$s = \quad \dots \text{get} \longrightarrow v_1 \longrightarrow \text{get} \longrightarrow v_2 \dots \quad \Rightarrow v_1 = v_2$$



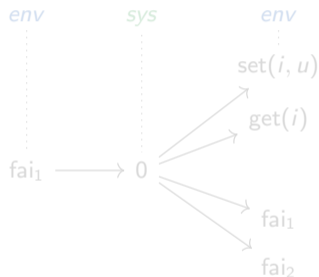
$$s = \quad \dots \text{set}(n) \longrightarrow \text{ok} \longrightarrow \text{get} \longrightarrow v \dots \quad \Rightarrow v = n$$

Structure of Trace Sets

- ▶ Two sides: system and environment

- ▶ Interfaces play as system.

- ▶ The environment is unpredictable hence non-deterministic:



- ▶ The system is deterministic:

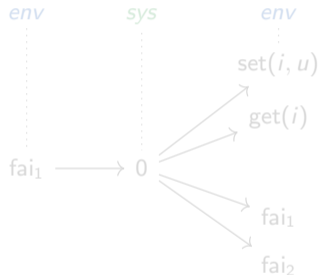


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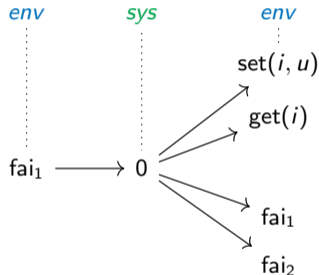


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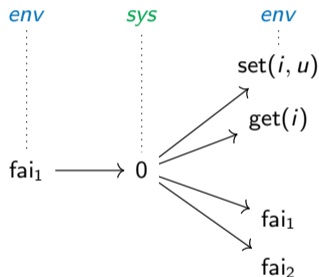


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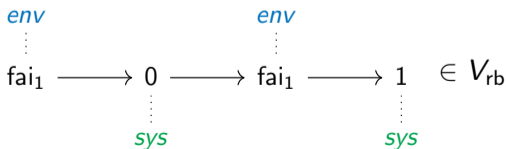
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Layer Specifications

An **layer specification** V_E over E is a **deterministic strategy** of type $\dagger E$.

That is, V_E is a set of $\dagger E$ plays that is:

- ▶ **non-empty,**
- ▶ **prefix-closed,**
- ▶ **deterministic**

Layer Interfaces

$$\begin{array}{l} \overline{\overline{M}} \\ L_2 = (F, V_F) \\ \overline{\overline{M}} \\ L_1 = (E, V_E) \end{array}$$

DEFINITION

A **layer interface** is a pair $L = (E, V_E : \dagger E)$.

Outline

Introduction

Layer Signatures: E

Implementations: $M : \dagger E \multimap F$

Layer Interfaces: $L = (E, V_E)$

Certified Layer Implementations: $L_1 \vdash M : L_2$

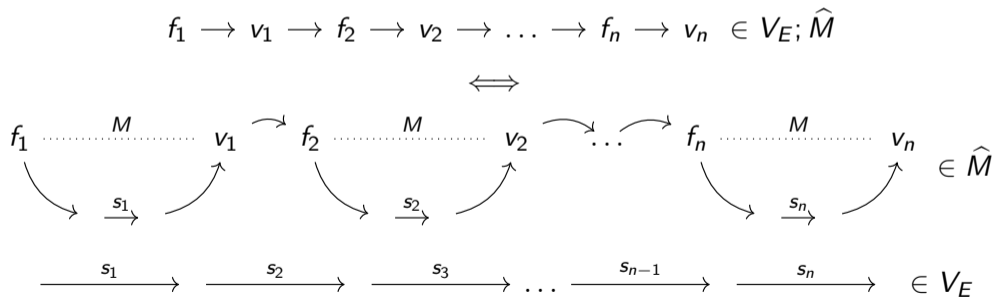
Non-Deterministic Layer Specifications: $L = (E, \mathcal{V}_E)$

Concurrent Layers: $L = (E, R, V_E)$

Conclusion

Certified Implementations

- ▶ $M : E_{rb} \rightarrow E_{bq}$ does not know rb semantics or bq semantics.
- ▶ Composing with V_{rb} “gives” the rb semantics to \hat{M} :



Certified Layer Implementations

DEFINITION

A **certified layer implementation** $L_E \vdash M : V_F$ consists of:

$$\begin{array}{lll} \text{Underlay:} & \text{Overlay:} & \text{Implementation:} \\ L_E = (E, V_E) & L_F = (F, V_F) & M : E \rightarrow F \end{array}$$

$$\begin{array}{l} \text{Correctness:} \\ V_F \subseteq V_E; \hat{M} \end{array}$$

EXAMPLE

$$(E_{rb}, V_{rb}) \vdash M : (E_{bq}, V_{bq})$$

“For every V_{bq} behavior there is some V_{rb} that can be used by M to implement the V_{bq} behavior”

Outline

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Conclusion

Non-Deterministic Layer Specifications

A **non-deterministic layer specification** \mathcal{V}_E for E is a non-empty set of $V_E : \dagger E$.

A **non-deterministic layer interface** is pair (E, \mathcal{V}_E) .

EXAMPLE (NON-DETERMINISTIC **rb** INITIALIZATION)

- ▶ **Bounded queue:** $\mathcal{V}_{\text{bq}} := \{V_{\text{bq}}\}$
- ▶ **Ring buffer:**

Deterministic:

$$V_{\text{rb}} := L_{\text{rb}}\#(\emptyset, 0, 0)$$

Non-Deterministic:

$$\mathcal{V}_{\text{rb}} := \{L_{\text{rb}}^S\#(f, c, c) \mid f \in \mathbb{U}^N, c < N\}$$

Non-Deterministic Certified Abstraction Layers

DEFINITION

A **non-deterministic certified abstraction layer** $L_E \vdash M : L_F$ consists of:

$$\begin{array}{lll} \text{Underlay:} & \text{Overlay:} & \text{Implementation:} \\ L_E = (E, \mathcal{V}_E) & L_F = (F, \mathcal{V}_F) & M : E \rightarrow F \end{array}$$

Correctness:

$$\forall V_E \in \mathcal{V}_E. \exists V_F \in \mathcal{V}_F. (E, V_E) \vdash M : (F, V_F)$$

EXAMPLE

$$(E_{rb}, \mathcal{V}_{rb}) \vdash M : (E_{bq}, \mathcal{V}_{bq})$$

Outline

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Conclusion

Certified Concurrent Layers

- ▶ A **concurrent layer interface** is a triple (E, R, V_E) where R is a **coherent congruence** between plays of $\dagger E$.
- ▶ R is essentially a “determinism preserving” equational theory:

$$s \cdot e_1 \cdot v_1 \cdot e_2 \cdot v_2 \cdot t \quad R \quad s \cdot e_2 \cdot v_2 \cdot e_1 \cdot v_1 \cdot t$$

- ▶ Implementations work on equivalence classes under coherent congruences:

$$M : \dagger_R E \multimap \dagger_S F$$

$$[s]_R \mapsto [t]_S$$

Check paper for details!

Equational Theories and \dagger -Coalgebras

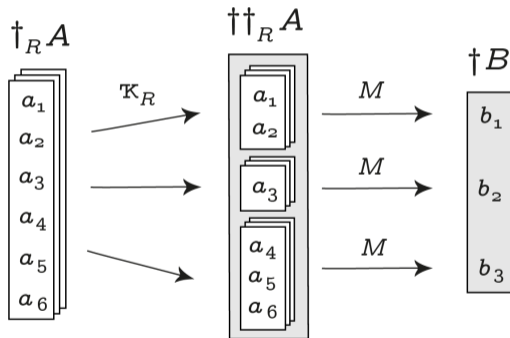
Given equational theory $R \in \text{Rel}(\dagger A, \dagger A)$
we construct a \dagger -Coalgebra:

$$(\dagger_R A, \kappa_R : \dagger_R \multimap \dagger\dagger_R)$$

Generalized regular extension:

$$M : \dagger_R A \multimap B$$

$$\dagger_R A \xrightarrow{\widehat{M}} \dagger B = \dagger_R A \xrightarrow{\kappa_A} \dagger\dagger_R A \xrightarrow{\dagger M} \dagger B$$



Certified Concurrent Layers

This allows us to:

- ▶ Reasoning up to the equational theory R
- ▶ Express independent products of layers

$$(E, R, V_E) \otimes (F, S, V_F) := (E \uplus F, R \otimes S, V_E \bullet V_F)$$

- ▶ Express specific patterns of state sharing (e.g. lock-based)
- ▶ Express the implementation of synchronization primitives (e.g. ticket lock)

Conclusion

- ▶ We have a novel way of building models of CAL
 - ▶ No explicit state
 - ▶ Rooted in linear logic
 - ▶ Extensible
- ▶ Promising direction in compositional semantics for reasoning about large systems.



New CAL [POPL '22] $\xrightarrow{\text{Semantics}}$ DeepSEA [OOPSLA '19] $\xrightarrow{\text{Compilation}}$ CompCertO [PLDI '21]

Thank you!

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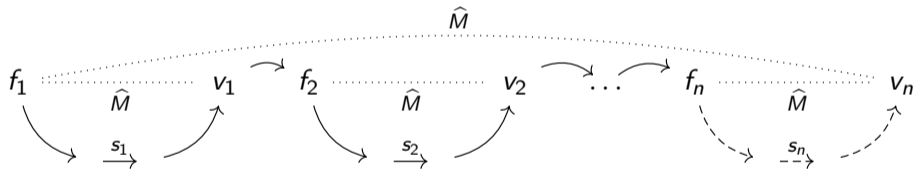
Thank you!

Layer Implementations are Regular Maps

Implementations are regular maps:

$$\widehat{M} : \dagger E \multimap \dagger F$$

Regular maps are linear maps that are “replayable”:



THEOREM (REDDY)

$$\dagger E \xrightarrow{\text{Reg}} \dagger F \cong \dagger E \multimap F$$

Layer Specifications are Stateful

$$V_{\text{Counter}} = \{\epsilon, \text{get}, \text{inc}, \text{get} \cdot 0, \text{inc} \cdot \text{ok}, \text{inc} \cdot \text{ok} \cdot \text{get}, \text{inc} \cdot \text{ok} \cdot \text{get} \cdot 1, \dots\}$$

State as Past

$$S_E = \text{plays of } V_E \quad \text{Initial: } \epsilon \quad s \xrightarrow{e.v} s \cdot e \cdot v \iff s \cdot e \cdot v \in V_E$$

