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Typed Cross-Module Compilation
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Abstract

Higher-order modules are very effective in structuring large programs and defining generic, reusable software components. Unfortunately, many compilation techniques for the core languages do not work across the module boundaries. As a result, few optimizing compilers support these module facilities well.

This paper exploits the semantic property of ML-style modules to support efficient cross-module compilation. More specifically, we present a type-directed translation of the MacQueen-Tofte higher-order modules into a predicative variant of the polymorphic λ-calculus $F_\omega$. Because modules can be compiled in the same way as ordinary polymorphic functions, standard type-based optimizations such as representation analysis immediately carry over to the module languages.

We further show that the full-transparency property of the MacQueen-Tofte system yields a near optimal cross-module compilation framework. By propagating various static information through the module boundaries, many static program analyses for the core languages can be extended to work across higher-order modules.
Typed Cross-Module Compilation

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1 Introduction

Modular programming has proven to be extremely valuable in the development and maintenance of large software systems [BHL94, Nel91, Geo97]. Many modern programming languages such as Modula-3 [Nel91] and Standard ML [MTH90, MTHM97] provide support for both core-level and module-level programming. The core language, in general, deals with the detailed implementation of algorithms in terms of data structures and control constructs. The module language, on the other hand, provides glue to organize large programs and to build generic and reusable components. A mature and scalable compiler must support both styles of programming well, generating decent code even for heavily modularized programs.

ML-style higher-order modules [MT94, HL94, Ler95] are widely recognized as one of the most powerful module constructs in existence today. Recent work on the type-theoretic foundations of ML modules [HL94, Ler94, MTHM97] has cleaned up many rough spots in the original design [MTH90]. Still, the semantics for higher-order modules involves the use of dependent types [Mac86, HM93] or translucent signatures [HL94, Ler94]. MacQueen and Tofte [MT94] have shown that even a small restriction on signature matching [Ler94, HL94] can significantly compromise the overall expressiveness (i.e., full transparency) of the underlying module language. It is fair to say that the type systems for higher-order modules is much more elaborate than (or at least very different from) those for the core-ML-like languages [DM82].

This semantic difference between the core and module languages poses great challenges to compiler writers. Although the module code itself seldom needs to be compiled efficiently, optimizations used for the core language must be compatible with the module constructs in order to have a coherent compiler. Unfortunately, many compilation techniques do not work on programs that use higher-order modules. In fact, most recent work on compiling functional languages have ignored issues on the necessary module support. Take the area of type-directed compilation as an example: recent work includes representation analysis [Ler92, Sha97a], type

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specialization [Cha92], intensional type analysis [HM95], typed closure conversion [MMH96], tagless garbage collection [Tol94], to name just a few. All of these are performed on the variants of core ML [DM82] or the polymorphic λ-calculus Fω  [Gir72, Rey74]. While they have all demonstrated that types can be used to make programs run faster and consume less space, it is not obvious how any of these would work in the presence of higher-order modules (which make use of dependent types).

Consider the module code in Figure 1, written in the SML syntax. Here, structure SA, SB, and SC are simple modules; signature ASIG and BSIG express the interface of structures; functor F (inside SB) and APP, also known as parameterized modules, are just functions from structures to structures. Functor specifications such as F inside BSIG use functor signatures to express the interface of functors. Structure SB and functor APP are examples of the so-called “higher-order” modules: structures (SB) can contain other functors as their components, and functors (APP) can take arbitrary structures as their arguments. Functors can only be applied to structures with compatible signatures, as in APP(SB); the result structure has an interface like that of the original functor body, but with proper instantiations.

It is easy to see why higher-order modules would break the type-based optimizations mentioned above. In the Fω  calculus, polymorphic functions such as the identity function \( \lambda t : \Omega. \lambda x : t.x \) always cleanly separate the type abstraction (\( \lambda \)) from the value abstraction (\( \lambda \)). Therefore, polymorphic functions in Fω  or core ML can be specialized to particular type arguments at compile time. Furthermore, both representation analysis [Ler92, Sha97a] and intensional type analysis [HM95] can be performed, inserting coercions or runtime type parameters at every type-application site. Higher-order modules, on the other hand, express both the type and value abstractions through a single construct (i.e., functor). A functor such as APP and SB.F takes mixed sets of types and values as its argument, and return another such set as its result. Functor applications such as APP(SB) cannot be type-specialized, because we do not know how to identify the exact type parameters in functors such as APP. Representation analysis and intensional type analysis are also hard to perform because of the pervasive use of dependent types.

Higher-order modules also make it very difficult to carry out static program analysis across the module boundaries. Because the module signature does not propagate any static information other than types, many existing techniques, such as constant propagation, function inlining [App92], partial evaluation [Jon91],
and constraint-based analysis [AH95], lose all their information at the functor-application boundaries. In the previous example, if we textually inline all functor applications in the source, we can deduce that the $f$ component in structure SC is equivalent to the following:

\[
\text{fun } f \ (x : \text{int}) = 3
\]

However, because inlining large functors can lead to code explosion, and moreover, modules often must be compiled separately, it is impractical to eliminate all functors by inlining. The challenge then is to deduce these properties statically while still supporting separate compilation.

This paper exploits the semantic property [HMM90] of ML-style modules to support efficient cross-module compilation. More specifically, we present a type-directed translation of the MacQueen-Tofte higher-order modules [MT94] into a predicative variant of the $\mathbb{F}_\omega$ calculus. Because modules can be compiled in the same way as ordinary polymorphic functions, all the type-based optimizations mentioned above immediately carry over to the module languages. The basic idea of our algorithm is similar to phase-splitting [HMM90]: we notice that every ML module can be split into a type part and a value part; the type (value) part of a structure includes all of its type (value) components plus the type (value) parts of its structure and functor components; the type part of a functor is a higher-order type function from the type part of its arguments to that of its result; the value part of a functor can be viewed as a polymorphic function quantified over the type part of its arguments; functor applications can thus be expressed as a combination of type application and value application as in the $\mathbb{F}_\omega$ calculus.

We further show that the full-transparency property of the MacQueen-Tofte system yields a near optimal cross-module compilation framework. Here, by full transparency, we mean that type information is always propagated optimally through all the module boundaries, so structures such as SC get exactly the same typing whether functor APP is textually inlined or separately compiled. By propagating other static information in the same way, we can extend most static program analyses for core languages to work across higher-order modules.

The main contributions of this paper are:

- As far as we know, our work is the first comprehensive and formal study on how to apply type-based compilation techniques [Ler92, Tol94, HM95, MMH96, Sha97a] to programs using ML-style modules. Our main result that ML-style modules can be compiled into an $\mathbb{F}_\omega$-like calculus is new and significant because immediately all type-based techniques for $\mathbb{F}_\omega$ become applicable to the module languages as well.

- Our translation of the MacQueen-Tofte system into the $\mathbb{F}_\omega$ calculus is the first such algorithm that deals with the essential features in the ML-like module languages. Several recent papers [HMM90, Bis95, Ler95] have attacked similar problems but with completely different motivations; they also impose severe restrictions to their module languages (e.g., no type abbreviation or sharing inside signatures [HMM90], no parameterized types [Bis95], and limited forms of functor arguments [Ler95]).

- Our compilation algorithm can handle the entire SML'97 language [MTTHM97] including both transparent and opaque signature matching. In fact, the algorithm has been implemented and released with the SML/NJ compiler since version 109.24 (January 9, 1997). As a result, all type-based optimizations in the compiler work across the higher-order module boundaries.

- We also describe a new algorithm that does both cross-module inlining and type specialization, even for functions with free value and type variables. Our algorithm supports fully transparent propagation of binding information, even across heavily functorized code. Other kinds of program analysis can be extended to work across higher-order modules in the same way.
To facilitate our presentation, we give a new and more complete formal definition for the MacQueen-Tofte higher-order modules. MacQueen and Tofte’s original semantics [MT94] does not address many important features such as type specifications, type declarations, and hidden module components. Our new semantics covers a much richer language and solves the remaining technical problems.

The rest of this paper is organized as follows: we first define an F∗-based target calculus (TGC) and an ML-style higher-order module calculus (NRC). The NRC calculus contains all the essential features in an ML-style module system. We give the static semantics for NRC and then present a type-directed translation from NRC to TGC. We show how to exploit the full-transparency property to support cross-module program analysis. Finally, we discuss implementation details, related work, and then conclude.

2 An F∗-based target calculus

Our target calculus TGC is a predicative variant [HMM90] of the polymorphic λ-calculus F∗. The syntax of TGC is given in Figure 2. Here, kinds classify type constructors (tycon); types classify terms. Declarations (dec) and the term let d in e are syntactic sugar introduced to simplify the presentation of our translation algorithm. Constructors of kind Ω name monotypes. The monotypes are generated from variables, Int, and through the arrow constructor (→). The application and abstraction constructors correspond to the function kind κ → κ′. The product and selection constructors correspond to the product kind {l :: κ, ..., l′ :: κ′}. Types in TGC include the monotypes, and are closed under products, function spaces, and polymorphic quantification. Following Harper and Morrisett [HM95], we use T(μ) to denote the corresponding monotype of the constructor μ. The terms are an explicitly typed λ-calculus with explicit constructor abstraction (Λ) and application forms. TGC terms also include the labeled product and selection terms; product terms such as {l = e, ..., l′ = e′} correspond to product types of {l :: κ, ..., l′ :: κ′}.

The static semantics for TGC, as summarized in Figure 4, consists of a collection of rules for constructor formation, constructor equivalence, type formation, type equivalence, term formation, and declaration forma-
\[
\Delta \vdash \mu_i :: \kappa_i \quad \Delta \vdash \mu'_i :: \kappa'_i \\
\Delta \vdash \{l = \mu_{i1}, \ldots, l' = \mu'_{i1}\} :: \{l :: \kappa_{i1}, \ldots, l' :: \kappa'_{i1}\} \quad \text{(cp prod)}
\]

\[
\Delta \vdash \mu_i :: \{l :: \kappa_i, \ldots\} \\
\Delta \vdash \mu_i.l :: \kappa_i \\
\Delta \vdash \{l = \mu_i.l, \ldots, l' = \mu_i.l'\} :: \mu_i :: \kappa_i' \\
\quad \text{(select)}
\]

\[
\Delta; \Gamma \vdash e_i :: \sigma_i \quad \Delta; \Gamma \vdash e'_i :: \sigma'_i \\
\Delta; \Gamma \vdash \{l = e_{i1}, \ldots, l' = e'_{i1}\} :: \{l :: \sigma_{i1}, \ldots, l' :: \sigma'_{i1}\} \\
\quad \text{(prod)}
\]

\[
\Delta; \Gamma \vdash e_i :: \{\ldots, l :: \sigma_{i1}, \ldots\} \\
\Delta; \Gamma \vdash e_i.l :: \sigma_i \\
\quad \text{(select)}
\]

Figure 4: Selected typing rules for TGC

3 Module semantics and translation

To show how we translate the ML-style modules into the TGC calculus, we choose a surface language (SFC) that is similar to the SML’97 module language [MTHM97] extended with the MacQueen-Tofte higher-order modules [MT94]. We divide the translation from SFC to TGC into two steps:

- First, we perform a series of syntactic transformations and normalizations, and then translate the SFC program into a normalized module calculus (NRC);
- Second, we translate the NRC program into the TGC calculus.

To make the paper more focused, we will only briefly explain the first step, and then concentrate on describing the NRC calculus and how we translate NRC into the TGC calculus. Appendix B gives more details about the SFC calculus and the SFC-to-NRC translation.

3.1 Normalization and the NRC calculus

The syntax of our normalized module calculus NRC is defined in Figure 5. During the SFC-to-NRC translation, each identifier in the surface language is alpha-converted and assigned a unique internal name, so an identifier (e.g., \( x_i \)) in NRC always consists of two parts: an external name (\( x \)) and an internal stamp (\( i \)). We use \( t, s \), and \( f \) to denote type, structure, and functor identifiers, and \( p_t, p_s, \) and \( p_f \) for the access paths.

The NRC module language includes standard constructs such as signatures \( (M_s) \), functor signatures \( (M_f) \), structure expression \( (m_s) \), and functor expressions \( (m_f) \). A signature contains a list of type, structure, and
functor specifications \((D)\). A type specification can either be a flexible one—specifying only the arity of the underlying type constructor; or it can be a type abbreviation. Type-sharing specifications in SFC are converted into type abbreviations [Ler96b]. A structure expression can be a structure path \(p_s\), a functor application \(f_i(s_i)\), a structure matched by a signature \(s_i : M_s\), or a definitional structure \(m_b\). Functors in NRC are higher-order because they can be passed as arguments or returned as results by other functors.

To simplify the presentation, we did not include value specification and value declaration in the current NRC calculus. We also used a rather simple type language where \(\kappa_c\) denotes type constructor and \(\kappa_c\) denotes its kind (i.e., the arity). These simplifications do not affect the generality of our algorithm since the main idea of our translation can be illustrated independent of these core-language features. Section 5 gives more details on how to handle value components and other advanced core-language features.

The translation from SFC to NRC does a series of normalizations that turn complex SFC constructs into simpler and more primitive NRC constructs. The most important transformation is to make explicit all enrichment coercions occurring at every signature matching (see Appendix B for details). After this transformation, a structure \(s_i\) in NRC will only match a signature \(M_s\) if the following are all satisfied: first, \(s_i\) must contain the same number of components as those in \(M_s\); second, each pair of corresponding components in \(s_i\) and \(M_s\) must have the same external and internal names and follow the same order; finally, each functor component in \(s_i\) must have a signature syntactically equivalent to its counterpart in \(M_s\). These invariants are reflected and enforced in NRC’s static semantics given in Section 3.2.

Another unusual feature of NRC is that functor body must be of form \(\text{struct} \ldots \text{end}\), i.e., a definitional structure expression marked syntactically as \(m_b\). This is exploited by the static semantics to ensure a one-to-one mapping between type stamps and their definitional type paths. To convert an arbitrary functor expression (say \(\text{funct} (s_i : M_s) m_b\)) into this form, the SFC-to-NRC translation wraps an extra layer around the functor body \(m_b\); the resulting functor body becomes:

\[
\text{funct} (s_i : M_s) \text{ struct } \text{ structure } R = m_b \text{ end.}
\]
Functor bodies inside functor signatures are transformed in the same way. Meanwhile, functor application such as $F(S)$ is translated into:

\[
\text{let structure } T = F(S) \text{ in } T.R \text{ end.}
\]

Finally, all module declarations inside the let expressions in SFC are pushed upwards and then turned into the NRC local declarations (see Appendix B for details).

### 3.2 Static semantics for NRC

Before presenting the translation from NRC to TGC, we first give a new and more complete formal semantics for the MacQueen-Tofte higher-order modules [MT94] in the context of NRC. Under our stamp-based approach, the “type” of a module—also called the modtype in this paper—is expressed as a pair of a signature and a realization. The signature captures the module skeleton such as names of its components and the kind and sharing information for type specifications. The realization describes the actual type definition for all the type paths $(p_b)$ in an NRC construct. The job of the static semantics is to infer and validate the semantic types for all NRC type paths, and then propagate this information to different modules.

Figure 6 defines the semantic objects used by our new semantics. Figure 7 gives a summary of all the semantic rules; we use a single set of deduction rules to describe both the static semantics and the translation algorithm. A deduction such as $W \vdash X : Y \Rightarrow Z$ has the following meaning: under the environment $W$, the NRC construct $X$ is elaborated into the semantic object $Y$ and translated into the TGC construct $Z$. In the rest of this paper, we use $\emptyset_N, \emptyset_R$, etc. to denote the empty environments; $\ast$ to denote the environment overlay; $\bullet$ to denote things that are irrelevant under the current rule; and $s_i, p_s$ to denote an access path that starts with an structure $s_i$ and ends with a tail path $p_s$. We also restrict our semantics to elaborate normalized NRC programs only; an NRC program is normalized if there are no duplicate bindings within each scope, and
\[
\begin{align*}
B \vdash D \leq D' & \quad (1) \\
B \vdash \text{sig } D \text{ end} \leq \text{sig } D' \text{ end} & \\
B \vdash \varepsilon \leq \varepsilon & \quad (3) \\
B \vdash \text{functor } f_i : M_f \leq \text{functor } f_i : M_f & \quad (4) \\
B \vdash M_s \leq M'_s & \quad (5) \\
B \vdash \text{structure } s_i : M_s \leq \text{structure } s_i : M'_s & \\
B \vdash \text{type } t_i : \kappa_c \leq \text{type } t_i : \kappa_c & \quad (7) \\
B \vdash \text{type } t_i : \kappa_c = \mu_c \leq \text{type } t_i : \kappa_c = \mu'_c & \quad (6) \\
\end{align*}
\]

Figure 8: Signature subsumption in NRC

all of its functor definitions have distinctly named formal parameters; these conditions are enforced by the SRC-to-NRC translation.

Returning to Figure 6, here, \(\mu_m\) is an internal “semantic” type constructor designed for type-checking. The only difference between \(\mu_m\) and the NRC type constructor \(\mu_c\) is that \(\mu_c\) might be a type path \(p\), but \(\mu_m\) cannot be. During the elaboration, formal type constructors in NRC are translated into type stamps of the form \(n(\kappa_c, \mu_c)\) where \(n\) is a stamp, \(\kappa_c\) is its kind, and \(\mu_c\) is a TGC type constructor—auxiliary information used solely for the NRC-to-TGC translation. The type equivalence relation \(\equiv_m\) on \(\mu_m\) is the standard structural equivalence except that two stamped types \(n(\kappa_c, \mu_c)\) and \(n'(\kappa'_c, \mu'_c)\) are equivalent if and only if \(n\) and \(n'\) are equal.

A realization can be a type realization \((r_i)\), a structure realization \((r_s)\), or a functor realization \((r_f)\). A type realization captures the actual definition of a type component; it is represented simply as the internal type constructor \(\mu_m\). A structure realization captures the detailed definitions of all the components in a structure; it is defined as a realization environment \((R)\) which maps from (type, structure, and functor) identifiers to realizations. A functor realization captures the typing relationship between the argument and the result of a functor; it is defined either as a realization closure \((m_b, B, A_t)\) or as a formal template \((A_t)\). In both cases, \(A_t\) contains auxiliary TGC type information maintained solely for the NRC-to-TGC translation.

The realization for a fully defined functor, e.g., \text{funct} \((s_i : M_b) m_b\), is a realization closure \((m'_b, B, A_t)\). The code part of the closure, \(m'_b\), is simply the actual functor body \(m_b\). The environment part of the closure is the current basis \(^1\) \(B\) (defined below). The realization for a formal functor parameter, e.g., \text{functor} \(\mathbb{F}\) inside \text{APP} in Figure 1, is defined as a formal template, marked as \((A_t)\); all we know about such functor is its signature.

The basis environment \(B\) is a tuple \((\Delta, N, D, R)\) where \(\Delta\) is an auxiliary TGC kind environment, \(N\) is a stamp environment, \(D\) is a specification environment (represented as NRC specifications), and \(R\) is a realization environment. The kind environment \(\Delta\) does not play any role for the static semantics; it is purely maintained for the NRC-to-TGC translation (mainly to simplify the technical proof). The stamp environment \(N\) records all the type stamps defined so far and maps each of them to its definitional type path. The specification environment \(D\) and the realization environment \(R\) form the actual modtype environment. Given a module access path \(p\), we can retrieve its modtype by looking it up in the corresponding environments; the result is abbreviated as \(B(p) = (M_x, r)\) where wild card “\(\_\)” implies either structure entity \((s)\) or functor entity \((f)\).

At any time during the elaboration, an NRC type \(\mu_c\) can be mapped into its actual semantic type \(\mu_m\),

\(^1\) Neither the kind environment nor the stamp environment is required here, but we include it anyway to simplify the notation.
Typing and translation of declaration(s): \[ B \vdash d : N; D; R \Rightarrow d_i \]

\[
\begin{align*}
\mu_m & = c2m(B, \mu_c) & \mu_m \text{ has kind } \kappa_c \\
B \vdash \text{type } t_i : \kappa_c = \mu_c : \emptyset_N; \{\text{type } t_i : \kappa_c = \mu_c\}; \{t_i \mapsto \mu_m\} \Rightarrow \varepsilon 
\end{align*}
\]

(9)

\[ B \vdash m_s : N; M_s; r_s \Rightarrow e_i \quad N' = \{n \mapsto s_i.p_i \mid p_i = N(n), n \in \text{Dom}(N)\} \]

(10)

\[ B \vdash \text{structure } s_i = m_s : N'; \{\text{structure } s_i : M_s\}; \{s_i \mapsto r_s\} \Rightarrow (s_i = e_i) \]

\[ B \vdash m_f : N'; M_f; r_f \Rightarrow e_i \quad N' \equiv \emptyset_N \]

(11)

\[ B \vdash \text{functor } f_i = m_f : \emptyset_N; \{\text{functor } f_i : M_f\}; \{f_i \mapsto r_f\} \Rightarrow (f_i = e_i) \]

\[ B \vdash \varepsilon : \emptyset_N; \emptyset_D; \emptyset_R \Rightarrow \varepsilon \]

(12)

\[ B \vdash d' : N'; D'; R' \Rightarrow d_i' \quad B \uplus (\emptyset_\Delta, N', D', R') \vdash d'' : N''; D'''; R'' \Rightarrow d_i'' \]

(13)

\[ B \vdash d'd''' : N' \uplus N''; D'D'''; R' \uplus R'' \Rightarrow d_i'd_i'' \]

\[ B \vdash d' : N'; D'; R' \Rightarrow d_i' \quad B \uplus (\emptyset_\Delta, N', D', R') \vdash d'' : N''; D'''; R'' \Rightarrow d_i'' \]

(14)

Typing and translation of module expression: \[ B \vdash m_- : N; M_-; r_- \Rightarrow e_i \]

\[ B(\beta) = (M_s, r_s) \quad B(s_i) = (M'_s, r_s) \quad B \vdash M'_s \leq M_s \]

(15)

(16)

\[ B \vdash \text{struct } d \text{ end } : N'; \text{sig } D' \text{ end } ; \text{Rol } B \uplus R' \Rightarrow \text{let } d_i \text{ in } e_i \]

(17)

\[ B \vdash \mu_s : \kappa_s = \kappa_i \quad \Delta = \{s_i : \kappa_i\} \quad s_i; s_i; B \uplus (\emptyset_\Delta, \emptyset_D, \emptyset_R) \vdash M_s : N; r_s \Rightarrow \sigma_i \]

\[ B \uplus (\emptyset_\Delta, \{\text{structure } s_i : M_s\}; \{s_i \mapsto r_s\}) \vdash m_b : \bullet; M'_s; r'_s \Rightarrow e_i \]

\[ (M'_s, r'_s) \Rightarrow \mu'_i; \sigma'_i A_i = (\lambda s_i : \kappa_i, \mu'_i, \sigma'_i) \\
rf = (m_b, B, A_i) \]

(18)

\[ B \vdash \text{funct } (s_i : M_s)m_b : \emptyset_N; \text{fsig } (s_i : M_s)M'_s; rf \Rightarrow \Delta s_i : \kappa_i, \lambda s_i : \sigma_i, e_i \]

\[ B(f_i) = (M_f, r_f) \quad B(s_i) = (M_s, r_s) \quad M_f = \text{fsig } (s_i : M_s)M'_s \]

\[ D' = \{\text{structure } s'_i : M_s\}; \quad \Delta' = \{s'_i \mapsto r_s\} \vdash (M_s, r_s) \Rightarrow \mu_i; \bullet \]

(19)

\[ \text{if } rf = (A_i) \text{ and } A_i = (\mu'_i, \bullet) \text{ then } \mu'_i[\mu_i]; e; B \uplus (\emptyset_\Delta, \emptyset_N, D', R') \vdash M'_s : N'; r'_s \Rightarrow \bullet \]

\[ \text{if } rf = (m'_b, B', \bullet) \text{ then } (\Delta \text{of } B', \text{Rol } B, \text{Rol } B' \uplus D', \text{Rol } B' \uplus R') \vdash m'_b : N'; \bullet; r'_s \Rightarrow \bullet \]

\[ B \vdash \text{fs } (s_i) : N'; M'_s; r'_s \Rightarrow \text{@}(f_i[\mu_i])s_i \]

Figure 9: Module semantics and its translation into TGC
Signature instantiation and translation: \[ \mu; p_x; B \vdash M_s : N; r_s \Rightarrow \sigma_t \]

\[
\begin{align*}
\mu; p_x; B \vdash D : N'; R' \Rightarrow \text{lt}\hspace{1em} & \hspace{1em} R'' = \text{Rot}B \cup R' \\
\mu; p_x; B \vdash \text{sig} D : N'; R'' \Rightarrow \{\text{lt}\} \hspace{1em} & \hspace{1em} (20)
\end{align*}
\]

\[
\begin{align*}
\mu; p_x; B \vdash D : N; R \Rightarrow \text{lt}\hspace{1em} & \hspace{1em} \mu; p_x; B \cup (\emptyset, N, D, R) \vdash D' : N'; R' \Rightarrow \text{lt} \\
\mu; p_x; B \vdash DD' : N \cup N'; R \cup R' \Rightarrow \text{lt}, \text{lt} \hspace{1em} & \hspace{1em} (21)
\end{align*}
\]

\[
\begin{align*}
\mu; p_x; B \vdash \varepsilon : \emptyset_N; \emptyset_R \Rightarrow \varepsilon \hspace{1em} & \hspace{1em} \mu_m = \text{c2m}(B, \mu_c) \hspace{1em} \mu_m \text{ has kind } \kappa_c \hspace{1em} R = \{t_i \mapsto \mu_m\} \hspace{1em} (23)
\end{align*}
\]

\[
\begin{align*}
\frac{n \not\in \text{Dom}(N\text{of}B)}{\mu; p_x; B \vdash \text{(type} t_i::\kappa_c = \mu_c) : \emptyset_N; R \Rightarrow \varepsilon} \hspace{1em} & \hspace{1em} (24)
\end{align*}
\]

\[
\begin{align*}
\mu; p_x; p_s.s_i; B \vdash M_s : N; r_s \Rightarrow \sigma_t \hspace{1em} & \hspace{1em} (\text{structure} \ s_i : M_s) : N; \{s_i \mapsto r_s\} \Rightarrow s_i : \sigma_t \hspace{1em} (25)
\end{align*}
\]

\[
\begin{align*}
\vdash M_s \Rightarrow \kappa_t \hspace{1em} & \hspace{1em} \Delta = \{s_i :: \kappa_t\} \hspace{1em} s_i; s_i : B \cup (\Delta, \emptyset_N, \emptyset_D, \emptyset_R) \vdash M_s : N; r_s \Rightarrow \sigma_t \\
\mu''_t = \mu_t.f_i \hspace{1em} & \hspace{1em} \mu''_i[s_i; \varepsilon] : B \cup (\Delta, N, \{\text{structure} \ s_i : M_s\}, \{s_i \mapsto r_s\}) \vdash M'_s : \bullet; \bullet \Rightarrow \sigma'_t \\
\sigma''_t = \forall s_i :: \kappa_t, \sigma_t \mapsto \sigma'_t \hspace{1em} & \hspace{1em} A_i = (\mu''_t, \sigma'') \hspace{1em} \tau_f = (A_i) \\
\mu; p_x; B \vdash \text{(functor} f_i : \text{fsig}(s_i : M_s)M'_s) : \emptyset_N; \{f_i \mapsto \tau_f\} \Rightarrow f_i : \sigma''_t \hspace{1em} (26)
\end{align*}
\]

Figure 10: Signature instantiation and its translation into TGC

and vice versa. Given a basis environment \( B = (N, D, R) \), the \text{c2m} operator converts \( \mu_c \) into a semantic type by replacing each type path \( p_i \) in \( \mu_c \) with its actual definition \( R(p_i) \); the result is denoted as \( \text{c2m}(B, \mu_c) \). Similarly, the \text{m2c} operator can convert a semantic type \( \mu_m \) back to the external format by replacing each stamped type \( n(\kappa_c, \mu_t) \) with its definitional type path \( N(n) \). The \text{m2c} operator is not used in the current semantics, but it is useful for inferring the signature of modules with value (i.e., \text{val}) components.

The most unusual aspect of our semantics is the rules for signature subsumption (see Rules 1–8 in Figure 8): they are much more restrictive than those used by MacQueen and Tofte [MT94]. To have one signature subsume another, both must contain the same number of components, following the same order (Rules 2 and 3); furthermore, the respective functor components must have syntactically equivalent signature (Rule 4). This restriction, which is critical to the NRC-to-TGC translation, ensures that each NRC functor can only replace another if they have precisely same signature. Nevertheless, the surface language (SFC) can still have the more general subsumption rules, but signature matching in SFC must have all subsumption coercions made explicit during the translation from SFC to NRC (see discussions on related topics in Section 3.1).

Another interesting aspect is the elaboration of functor application (see Rule 19 in Figure 9). Functor application \( f_i(s_i) \) in NRC requires that the argument structure \( s_i \) have the syntactically same signature \( M_s \) as the formal parameter of \( f_i \). This again requires that signature matching at each functor application be made explicit during the SFC-to-NRC translation. The actual application is then done by applying the functor realization \( r_f \) of \( f_i \) to the realization \( r_s \) of \( s_i \). If \( f_i \) is a formal functor, that is, \( r_f \) is a realization template \( (A_i), \)
we deduce the result realization through instantiation of \( f_i \)'s body signature \( M^i_{s'} \); if \( r_f \) is a realization closure \((m^i_{s'}, R', A_t)\), we get the result by re-elaborating the functor body \((f_i)\).

Because NRC does not have datatypes, new stamped types are only generated during signature instantiation (see Figure 10). In fact, only flexible type specifications are assigned new stamped types (see Rule 24). To maintain the mapping from a new stamp to its definitional type path, the instantiation procedure always memoizes the access path \((p_a)\) for the current component.

To reason about the static semantics, we first define a set of functions and notations used in the formal development. Function \textsf{freeStamps} returns the set of free stamps occurred inside a semantic object. Because stamps only occur free inside \( \mu_m \), the free stamps in a realization can be calculated as follows:

\[
\text{freeStamps}(r_t) = \text{freeStamps}(\mu_m) \quad \text{if} \quad r_t = \mu_m; \\
\text{freeStamps}(r_s) = \cup_{r \in \text{freeStamps}(r)} \quad \text{assuming} \quad r_s = R; \\
\text{freeStamps}(r_f) = \text{freeStamps}(\text{Rot}B) \quad \text{if} \quad r_f = (\bullet, B, \bullet); \quad \text{or} \quad \emptyset_N \quad \text{if} \quad r_f = (A_t).
\]

Function \textsf{defPaths} returns the set of access paths defined by a specification environment (or a realization

}\]
environment or an NRC module term). For example, the access paths defined by a realization environment can be calculated as follows:

\[
defPaths(r) = \bigcup_{x \in \text{Dom}(\mathcal{R})} \{x \} \cup \{x.p \mid p \in \text{defPaths}(\mathcal{R}(x))\} \text{ if } r = \mathcal{R}; \text{ or } \emptyset, \text{ otherwise.}
\]

Function freePaths returns the set of access paths occurred free in a specification environment (or a signature or a module term), taking consideration of removing those locally defined paths. The freePaths operation is always closed under the prefix operation. Finally, we say that two semantic objects are syntactically equivalent if they match precisely according to the definition in Figure 5 and 9; we then define that two realization environments \( \mathcal{R} \) and \( \mathcal{R}' \) are consistent with each other if for each \( p \in (\text{defPaths}(\mathcal{R}) \cap \text{defPaths}(\mathcal{R}')) \), realization \( \mathcal{R}(p) \) and \( \mathcal{R}'(p) \) are syntactically equivalent; similarly, two specification environments \( \mathcal{D} \) and \( \mathcal{D}' \) are consistent if for each \( p \in (\text{defPaths}(\mathcal{D}) \cap \text{defPaths}(\mathcal{D}')) \), specification \( \mathcal{D}(p) \) and \( \mathcal{D}'(p) \) are syntactically equivalent.

**Definition 3.1 (normalized programs and environments)**

- An NRC program fragment \( X \) (e.g., expression, declaration) is normalized if there are no duplicate bindings within each scope, and all of its functor definitions have distinctly named formal parameters.

- An NRC program fragment \( X \) (e.g., signature, expression, declaration) is normalized with respect to basis \( \mathcal{B} = (\Delta, \mathcal{N}, \mathcal{D}, \mathcal{R}) \) if \( X \) is normalized and it does not rebind any functor parameter names in \( (\mathcal{D}, \mathcal{R}) \), nor does it redefine any identifiers in \( \text{Dom}(\mathcal{R}) \).

- An environment \( (\mathcal{D}, \mathcal{R}) \) is normalized if (1) for each \( x \) in \( \mathcal{D} \), \( \mathcal{D}(x) \) is normalized, and (2) given any two functor paths \( p_f \) and \( p'_f \) in \( \text{defPaths}(\mathcal{D}) \) and suppose \( M_f = \mathcal{D}(p_f) \) and \( M'_f = \mathcal{D}(p'_f) \) then either \( (M_f, \mathcal{R}(p_f)) \) and \( (M'_f, \mathcal{R}(p'_f)) \) are syntactically equivalent, or all functor signatures in \( M_f \) and \( M'_f \) have different parameter names.

**Definition 3.2 (well-formed semantic objects)**

- A basis \( \mathcal{B} \) is well-formed if its modtype environment \( (\text{Def} \mathcal{B}, \text{Ref} \mathcal{B}) \) is well-formed with respect to \( \mathcal{B} \).

- A modtype environment \( (\mathcal{D}', \mathcal{R}') \) is well-formed with respect to basis \( \mathcal{B} = (\Delta, \mathcal{N}, \mathcal{D}, \mathcal{R}) \) if (1) \( (\mathcal{D}', \mathcal{R}') \) is normalized, and \( \mathcal{D}' \) is consistent with \( \mathcal{D} \) and \( \mathcal{R}' \) is consistent with \( \mathcal{R} \); (2) \( \text{freeStamps}(\mathcal{R}') \subseteq \text{Dom}(\mathcal{N}) \), and for each \( n \in \text{freeStamps}(\mathcal{R}') \), if \( \mathcal{N}(n) = p_t \) then \( p_t \in \text{defPaths}(\mathcal{R}') \); (3) \( \text{defPaths}(\mathcal{D}') \subseteq \text{defPaths}(\mathcal{R}') \), and for each type component \( p_t \in \text{defPaths}(\mathcal{D}') \), \( p_t \) is well-formed inside \( (\mathcal{D}', \mathcal{R}') \); for each module component \( p_m \in \text{defPaths}(\mathcal{D}') \), the modtype \( (\mathcal{D}'(p_m), \mathcal{R}'(p_m)) \) is well-formed with respect to \( \mathcal{B} \).

- A type component \( p_t \) inside environment \( (\mathcal{D}, \mathcal{R}) \) is well-formed if suppose \( D(p_t) \) is a type specification with kind \( \kappa_c \) and (optional) type definition \( \mu_c \), and \( R(p_t) = \mu_m \), then \( \mu_m \) has kind \( \kappa_c \), and if \( \mu_m' \) is the result of replacing each free type path \( p_t' \in \mu_c \) with \( R(p_t') \), then \( \mu_m \equiv \mu_m' \).

- A structure modtype \( (M_s, r_s) \) is well-formed with respect to basis \( \mathcal{B} \) if suppose \( M_s = \text{sig} \mathcal{D}' \text{ end} \) and \( r_s = \mathcal{R}' \), then the environment \( (\mathcal{D}', \mathcal{R}') \) is well-formed with respect to \( \mathcal{B} \).

- A functor modtype \( (M_f, r_f) \) is well-formed with respect to basis \( \mathcal{B} = (\Delta, \mathcal{N}, \mathcal{D}, \mathcal{R}) \) if assuming \( r_f = (A_i) \), then \( \text{freePaths}(M_f) \subseteq \text{defPaths}(\mathcal{R}) \); or assuming \( r_f = (m_b, B', A_i) \) where \( B' = (\bullet, \bullet, \mathcal{D}', \mathcal{R}') \), let \( M_f = \text{fsig}(s_i : M_s)M_s' \) and \( m_f = \text{funct} (s_i : M_s)m_b \), then \( m_f \) is normalized with respect to \( B' \), and \( \text{freePaths}(m_f) \subseteq \text{defPaths}(\mathcal{R}') \), and \( (\mathcal{D}', \mathcal{R}') \) is well-formed with respect to \( \mathcal{B} \).
Lemma 3.3 Given a well-formed basis $B = (\Delta, N, D, R)$, an NRC signature $M_s$, a TGC constructor $\mu_s$, if $M_s$ is normalized with respect to $B$ and $\mu_s; \varepsilon; B \vdash M_s : N''; r_s \Longrightarrow \bullet$, then $\text{Dom}(N') \cap \text{Dom}(N') = \emptyset$, and $\text{freePaths}(M_s) \subseteq \text{defPaths}(R)$, and modtype $(M_s, r_s)$ is well-formed with respect to $B' = (\Delta, N \uplus N', D, R)$.

Proof: By structural induction on the signature expression $M_s$. The side condition $\mu_m = c2m(B, \mu_c)$ in Rule 23 guarantees that all free type paths in $M_s$ is defined in $R$. □

Lemma 3.4 Given a well-formed basis $B = (\Delta, N, D, R)$, suppose $d$ is an NRC declaration, if $d$ is well-formed with respect to $B$ and $B \vdash d : N' ; D' ; R' \Longrightarrow \bullet$, then $\text{Dom}(N') \cap \text{Dom}(N) = \emptyset$, and $\text{Dom}(D') \cap \text{Dom}(D) = \emptyset$, and $\text{Dom}(R') \cap \text{Dom}(R) = \emptyset$, and $\text{freePaths}(d) \subseteq \text{defPaths}(R)$, and the basis $(\Delta, N \uplus N', D \uplus D', R \uplus R')$ is well-formed as well. Similarly, suppose $m_\bullet$ is an NRC expression, if $m_\bullet$ is normalized with respect to $B$ and $B \vdash m_\bullet : N' ; M'_\bullet ; r'_\bullet \Longrightarrow \bullet$, then $\text{Dom}(N') \cap \text{Dom}(N) = \emptyset$, and $\text{freePaths}(m_\bullet) \subseteq \text{defPaths}(R)$, and $(M'_\bullet, r'_\bullet)$ is well-formed with respect to basis $(\Delta, N \uplus N', D, R)$.

Proof: Using Lemma 3.3 and by induction on derivation trees [Win93, Chapter 3]. □

The first property we can show is that our static semantics always produce typings that are unique up to the $\alpha$-renaming of type stamps. More specifically, we say two stamp environments $N$ and $N'$ are $\alpha$-equivalent if there exists a one-to-one mapping $\varphi$ from $\text{Dom}(N)$ to $\text{Dom}(N')$ such that for each $n \in \text{Dom}(N)$, $N(n)$ is syntactically equivalent to $N'(\varphi(n))$. We also say that two basis $B = (\Delta, N, D, R)$ and $B' = (\Delta', N', D', R')$ are $\alpha$-equivalent if (1) $N$ and $N'$ are $\alpha$-equivalent under the mapping $\varphi$; (2) $R' = \varphi(R)$; and (3) $D$ and $D'$ are syntactically equivalent.

Lemma 3.5 Given two well-formed basis $B$ and $B'$, an NRC signature $M_s$, a TGC constructor $\mu_s$, and a path $p_x$, suppose $B$ and $B'$ are $\alpha$-equivalent, and $M_s$ is normalized with respect to $B$ and $B'$, then if both $\mu_s; p_x; B \vdash M_s : N; r_s \Longrightarrow \bullet$ and $\mu_s; p_x; B' \vdash M_s : N'; r'_s \Longrightarrow \bullet$ are true, then $\text{NoF}B \uplus N$ and $\text{NoF}B' \uplus N'$ are $\alpha$-equivalent under a mapping $\varphi$, with $r_s = \varphi(r'_s)$.

Proof: By structural induction on signature expression. □

Theorem 3.6 (unique typing) Suppose $B$ and $B'$ are two well-formed basis, $m_\bullet$ is an NRC module expression, $d$ is an NRC module declaration, suppose $B$ and $B'$ are $\alpha$-equivalent, both $m_\bullet$ and $d$ are normalized with respect to $B$ and $B'$, then (1) if both $B \vdash m_\bullet : N; M_\bullet; r_\bullet \Longrightarrow \bullet$ and $B' \vdash m_\bullet : N'; M'_\bullet; r'_\bullet \Longrightarrow \bullet$ are true, then $M_\bullet$ and $M'_\bullet$ are syntactically equivalent, and $\text{NoF}B \uplus N$ and $\text{NoF}B' \uplus N'$ are $\alpha$-equivalent under a mapping $\varphi$, with $r_\bullet = \varphi(r'_\bullet)$; (2) if both $B \vdash d : N ; D ; R \Longrightarrow \bullet$ and $B' \vdash d : N' ; D' ; R' \Longrightarrow \bullet$ are true, then $B \uplus (\emptyset_\Delta, N, D, R)$ and $B' \uplus (\emptyset_\Delta, N', D', R')$ are $\alpha$-equivalent.

Proof: By induction on derivation trees and Lemma 3.5. □

We can also show that under our static semantics, elaboration of NRC programs always terminates.

Theorem 3.7 (termination) Suppose $B$ is a well-formed basis and $d$ is an NRC declaration, if $d$ is normalized with respect to $B$, then elaboration $B \vdash d : N ; D ; R \Longrightarrow \bullet$ always terminates. Similar proposition holds for module expressions.

Proof: We relate the derivation tree of our static semantics with the derivation tree in an environment-based operational semantics for a simply typed $\lambda$-calculus (extended with labelled records and integers). Each functor realization in our semantics relates to a function closure that calculates the total number of functor applications
performed when the functor is applied. An infinite derivation tree under our semantics would then correspond to an infinite derivation for evaluating a simply typed λ-expression. This contradicts with the fact that simply typed λ-calculus is strongly normalized.

The static semantics for NRC satisfies a very nice full-transparency property: a functor application is assigned the same typing whether we compile it as is or by textually inlining the functor body. Full transparency opens up the possibility of embedding NRC into an F_τ-like calculus such as TGC. After all, F_τ shares a similar property: given a term \( e = \Lambda t :: \kappa.e_1 \) and a constructor \( \mu \) of kind \( \kappa \), type application \( e[\mu] \) always has the same type as the result of inlined application \( [\mu/t]e_1 \) where \( [\mu/t] \) is a substitution mapping \( t \) to \( \mu \). The main challenge is then to model functors using type abstraction (\( \Lambda \)) and value abstraction (\( \lambda \)) in TGC.

## 3.3 Translation from NRC to TGC

The NRC-to-TGC translation uses the same set of deduction rules as in the static semantics (see Figures 9 to 11). There are two key ideas behind our algorithm:

- First, functor application \( f_i(s_i) \) in NRC always requires that the argument \( s_i \) has exactly the same signature as the formal parameter of \( f_i \). NRC also uses a very restricted set of signature subsumption rules where functors can only match if they have same functor signatures. These restrictions allow us to use the signature to guide our translation.

- Second, an NRC module can be split into a type part and a value part. We use the signature (e.g., \( M_s \)) rather than the modtype to guide splitting. The type (value) part of a structure includes its "type" (value) components plus the type (value) parts of its structure and functor components. By "type" components, we include only those with flexible type specifications in \( M_s \) (not those type-abbreviation specs).

The type part of a functor is a higher-order type function from the type part of its arguments to that of its result; the value part of a functor is a polymorphic function quantified over the type part of its arguments; functor applications can thus be expressed as a combination of type application and value application as in the TGC calculus.

Rules 9-19 in Figure 9 give the translation from the NRC module declarations (expressions) to the TGC declarations (expressions). All module declarations (except type declarations) are translated into the TGC value declarations. Module access path is translated into TGC record selection (Rule 15). We take the liberty of using the same \( p_a \) and \( p_f \) to denote the TGC selection terms such as \( x_i \), \( \cdots s_i \) and \( f_i \), \( \cdots f_i \). Definitional structure \texttt{struct...end} is translated into record construction in TGC (Rule 17).

Each NRC functor, \texttt{funct}(\( s_i : M_s \))\,\texttt{m_b}, is translated into a TGC polymorphic function, \( \Lambda s_i :: \kappa_i, \lambda s_i :: \sigma_i.e_i \) (see Rule 18). Here, we assume that type and value identifiers in TGC belong to different name space so we can use the same \( s_i \) to name both without causing confusion (we can always tell the identifier status in TGC). We use the signature-instantiation procedure in Figure 10 to split functor parameter into two parts: its type part is a type parameter \( (s_i) \) of kind \( \kappa_i \); its value part is a value parameter \( (s_i) \) of type \( \sigma_i \). Kind \( (\kappa_i) \) can be inferred from the signature alone (see Rules 27–34 in Figure 11), and once again only flexible constructors are included in the type part (Rules 28 vs 29).

If we name the type part of the functor parameter as a TGC type constructor "\( s_i \)" of kind \( \kappa_i \), all its components can be assigned a TGC tycon as well. This is again done by the signature instantiation: the \( \mu_i \) on the left-hand side of Rules 20–26 denote the TGC tycon of the enclosing structure. For example, according
to Rule 24, the flexible tycon \( t_i \) is translated into a stamped type \( n(\kappa_i, (\mu_i, t_i)) \) where \( n \) is a new stamp, and the selection constructor \( \mu_i, t_i \) is the corresponding TGC tycon for the component \( t_i \).

After we instantiate the parameter signature, the functor body \( m_b \) is elaborated into a structure realization \( r'_b \). The type part of this functor is expressed as a tycon \( \lambda s_i : \kappa_i, \mu_i \) where \( \mu_i \) is the type part of \( m_b \). This information is memoized inside the functor realization \( r_f \) for future use (e.g., Rule 36). The type part of \( m_b \) is calculated by the procedure defined in Figure 11: given a structure with signature \( M_s \) and realization \( r_s \), its type part is simply a TGC product constructor, counting only those flexible type components (Rule 39 vs. Rule 40). The \( \text{m2t} \) operator in Rule 40 translates a semantic type \( \mu_m \) into the TGC tycon \( \mu_t \) by replacing all instances of stamped types \( n(\kappa'_c, \mu'_i) \) with \( \mu'_i \).

Translating functor applications is much simpler (Rule 19). A functor application \( f_i(s_i) \) is translated into a TGC expression \( @(f_i(\mu_i))s_i \). Here, the value part of functor \( f_i \) is translated into a TGC polymorphic function named \( f'_i \); the value part of structure \( s_i \) is translated into a TGC record named \( s'_i \); polymorphic function \( f_i \) is applied to the type part of structure \( s_i \), which is a TGC tycon \( \mu_t \) extracted from \( s_i \)’s modtype \( (M_s, r_s) \).

To prove the correctness of our translation, we need to relate the basis environment in NRC with the kind and type environments in TGC. Given a basis \( B \), we can derive its corresponding TGC environments as follows: the kind environment \( \Delta \) is just the \( \Delta \) component maintained inside \( B \); the type environment \( \Gamma \) is calculated by applying the procedure defined in Figure 11, assuming \( \text{Rod} B \models \text{Rod} B \Rightarrow \bullet \); then we convert the list of record fields \( lts \) into a TGC type environment in a straightforward manner. In the following, we state the type preservation theorem and sketch its proof.

**Definition 3.8** A well-formed basis \( B = (\Delta, N, D, R) \) preserves TGC typing if

- for each type component \( p_i \in \text{defPaths}(D) \), suppose \( D(p_i) \) has kind \( \kappa_i \), and \( \mu_i = \text{m2t}(R(p_i)) \), then \( \Delta \triangleright \mu_i :: \kappa_i \);
- for each structure component \( p_s \in \text{defPaths}(D) \), suppose \( M_s = D(p_s) \) and \( r_s = R(p_s) \) and \( \models M_s \Rightarrow \kappa_t \) and \( \models (M_s, r_s) \Rightarrow \mu_i; \sigma_t \), then \( \Delta \triangleright \mu_i :: \kappa_t \) and \( \Delta \triangleright \sigma_t \);
- for each functor component \( p_f \in \text{defPaths}(D) \), suppose \( M_f = D(p_f) \) and \( r_f = R(p_f) \) and \( \models M_f \Rightarrow \kappa_i \) and \( \models (M_f, r_f) \Rightarrow \mu_i; \sigma_i \), then there exists TGC entities \( \kappa'_i, \mu'_i, \sigma'_i \) such that \( \kappa_i = (\kappa'_i \rightarrow \kappa''_i) \) and \( \Delta \triangleright \mu_i :: (\exists \kappa_i. \kappa'_i) \) and \( \Delta \triangleright \sigma_i :: (\forall \sigma_i. \sigma'_i) \); furthermore, if \( r_f = (m'_f, B', \bullet) \), then \( B' \) preserves TGC typing as well.

**Definition 3.9** Given two well-formed basis \( B = (\Delta, N, D, R) \) and \( B' = (\Delta', N', D', R') \), we say that \( B \) is related to \( B' \) via a TGC substitution \( \rho \) (mapping TGC type variables to TGC type constructors) if

- both \( B \) and \( B' \) preserve TGC typings;
- \( \text{Dom}(\rho) \subseteq \text{Dom}(\Delta) \) and \( \text{Dom}(\rho) \cap \text{Dom}(\Delta') = \emptyset \), and for each \( x \) in \( \text{Dom}(\rho) \), suppose \( \Delta(x) = \kappa_i \) then \( \Delta' \triangleright \rho(x) :: \kappa_i \);
- for each type component \( p_i \in (\text{defPaths}(D) \cap \text{defPaths}(D')) \), both \( D(p_i) \) and \( D'(p_i) \) have the same kind \( \kappa_i \); furthermore, let \( \mu_i = \text{m2t}(R(p_i)) \) and \( \mu_i' = \text{m2t}(R'(p_i)) \), then \( \Delta' \triangleright \rho(\mu_i) :: \mu'_i :: \kappa_i \);
- for each module component \( p_m \in (\text{defPaths}(D) \cap \text{defPaths}(D')) \), both \( D(p_m) \) and \( D'(p_m) \) have the same signature \( M_r \); furthermore, if \( \models M_r \Rightarrow \kappa_i \) and \( \models (M_r, R(p_m)) \Rightarrow \mu_i; \sigma_t \) and \( \models (M_r, R'(p_m)) \Rightarrow \mu'_i; \sigma'_t \), then \( \Delta' \triangleright \rho(\mu_i) :: \mu'_i :: \kappa_i \) and \( \Delta' \triangleright \rho(\sigma_t) :: \sigma'_t \).
Lemma 3.10 Given a well-formed basis $B = (\Delta, N, D, R)$, a TGC type constructor $\mu_t$, a path $p_x$, and a signature $M_s$, suppose $B$ preserves TGC typing, also suppose $\vdash M_s \Rightarrow \kappa_t$ and $\Delta \sigma_t \models \kappa_t$ and $\mu_t; p_x; B \vdash M_s : N; r_s \Rightarrow \sigma_t$ and $\vdash (M_s, r_s) \Rightarrow \mu_t; \sigma_t$, then $\Delta \sigma_t \models \mu_t \equiv \mu_t' \equiv \kappa_t$ and $\Delta \sigma_t \equiv \sigma_t$.

Proof: By structural induction on the signature expression $M_s$. □

Lemma 3.11 Given two well-formed basis $B$ and $B'$, an NRC signature expression $M_s$, two TGC type constructors $\mu_t$ and $\mu_t'$, and an NRC path $p_x$, suppose $B$ is related to $B'$ via a TGC substitution $\rho$, also suppose $\vdash M_s \Rightarrow \kappa_t$ and $\Delta \rho \cdot B' \models \mu_t \equiv \mu_t' \equiv \kappa_t$ and $\mu_t; p_x; B \vdash M_s : N; r_s \Rightarrow \sigma_t$ and $\mu_t'; p_x; B' \vdash M_s : N'; r_s' \Rightarrow \sigma_t'$, then $\Delta \rho \cdot B' \models \rho(\sigma_t) \equiv \sigma_t'$.

Proof: By structural induction on the signature expression $M_s$. The key insight is that the TGC type $(\sigma_t)$ of a modtype can be completely determined by its signature plus its corresponding TGC tycon $(\mu_t)$. □

Lemma 3.12 Given a well-formed basis $B = (\Delta, N, D, R)$ and an NRC path $p_x$, suppose $B$ preserves TGC typing, then for each structure component $p_x$ in defPaths($D$), assume $D(p_x) = M_s$ and $R(p_x) = r_s$ and $\vdash M_s \Rightarrow \kappa_t$ and $\vdash (M_s, r_s) \Rightarrow \mu_t; \sigma_t$, let $s_i$ be a TGC type variable not in Dom($\Delta$) and $\Delta' \equiv \{ s_i : \kappa_t \}$, also let $B' = B \cup \{ \Delta', \emptyset_N, \emptyset_D, \emptyset_R \}$, then if $s_i; p_x; B' \vdash M_s : N'; r_s' \Rightarrow \sigma_t'$ and $\mu_t; p_x; B \vdash M_s : N''; r_s'' \Rightarrow \sigma_t''$, we have $\Delta \rho \cdot B' \models (\mu_t[s_i](\sigma_t)) \equiv \sigma_t''$.

Proof: By a straightforward application of Lemma 3.11. □

Lemma 3.13 Given well-formed basis $B$ and $B'$, if $B$ is related to $B'$ via a TGC substitution $\rho$, then

- for each NRC module expression $m_-$, if $m_-$ is normalized with respect to $B$ and $B'$, and both $B \vdash m_- : N ; M_- ; r_- \Rightarrow \bullet$ and $B' \vdash m_- : N' ; M'_- ; r'_- \Rightarrow \bullet$ are true, then $M_-$ and $M'_-$ are syntactically equivalent; furthermore, if $\vdash M_- \Rightarrow \kappa_t$ and $\vdash (M_- , r_-) \Rightarrow \mu_t; \sigma_t$ and $\vdash (M'_-, r'_-) \Rightarrow \mu_t'; \sigma_t'$, then $\Delta \rho \cdot B' \models \rho(\mu_t) \equiv \mu_t' \equiv \kappa_t$ and $\Delta \rho \cdot B' \models \rho(\sigma_t) \equiv \sigma_t'$.

- for each NRC module declaration $d$, if $d$ is normalized with respect to $B$ and $B'$, and both $B \vdash d : N ; D ; R \Rightarrow \bullet$ and $B' \vdash d : N' ; D' ; R' \Rightarrow \bullet$ are true, then $D$ and $D'$ are syntactically equivalent; furthermore, basis $B \cup (\emptyset_\Delta, N, D, R)$ is related to $B \cup (\emptyset_\Delta, N', D', R')$ via the TGC substitution $\rho$ as well.

Proof: By induction on the derivations and using Lemma 3.10 to 3.12. □

Theorem 3.14 (type preservation) Given a well-formed basis $B$, suppose $B$ preserves TGC typing, and $\Delta$ and $\Gamma$ are its derived TGC kind and type environments, then

- for each NRC module expression $m_-$, if $m_-$ is normalized with respect to $B$ and $B \vdash m_- : N ; M_- ; r_- \Rightarrow \epsilon_t$ and $\vdash M_- \Rightarrow \kappa_t$ and $\vdash (M_- , r_-) \Rightarrow \mu_t; \sigma_t$, then $\Delta \mu_t \equiv \kappa_t$ and $\Delta; \Gamma \vdash \epsilon_t \equiv \sigma_t$.

- for each NRC module declaration $d$, if $d$ is normalized with respect to $B$ and $B \vdash d : N ; D ; R \Rightarrow d_\epsilon$, and $\Gamma'$ is the derived TGC type environment constructed from $R$ and $D$, then $B \cup (\emptyset_\Delta, N, D, R)$ preserves TGC typing and $\Delta; \Gamma \vdash d_\epsilon : \Gamma'$. 
Proof: By induction on the derivations. The only nontrivial case is on derivations ended with Rule 19. To deduce \( B \vdash f_i(s_i) : \bullet ; M'_i ; r'_i \Rightarrow @(f_i[\mu])s_i \), we must already have \( B(f_i) = (M_f, r_f) \) and \( B(s_i) = (M_s, r_s) \) and \( M_f = \text{fsig}(s'_i : M_s') \) and \( D' = \{ \text{structure } s'_i : M_s' \} \) and \( R' = \{ s'_i \mapsto r'_i \} \) and \( M_s \Rightarrow \kappa_i \) and \( M'_i \Rightarrow \kappa'_i \) and \( (M_s, r_s) \Rightarrow \mu_i; \sigma_i \). Assuming \( B(M'_i, r'_i) \Rightarrow \mu'_i; \sigma'_i \), then we need to prove both \( B \vdash \mu'_i : \kappa'_i \) and \( \Delta; \Gamma \vdash @(f_i[\mu])s_i : \sigma'_i \).

In the case of \( r_f = (A_1, \text{aux}) \), the auxiliary TGC information \( A_1 \) must be of form \((\lambda s'_i :: \kappa_i; \mu_i''', \forall s'_i :: \kappa_i; \sigma'_i''') \Rightarrow \sigma'_i'''' \); furthermore, such functor realization must be introduced by Rule 26 in Figure 10. Thus if we let \( \Delta' = \{ s'_i :: \kappa_i \} \), we should also have \( s'_i ; s'_i ; B \cup (\Delta', \emptyset_N, \emptyset_D, \emptyset_n) \vdash M_s : \bullet ; r'''' \Rightarrow \sigma'''' \). From Lemma 3.10, we have \( \vdash (M_s, r''') \Rightarrow s'_i ; \sigma'''' \); because \( (M_s, r''') \vdash \mu_i ; \sigma_i \), from Lemma 3.12, we can deduce \( B \vdash [\mu_i / s'_i](\sigma''') \equiv \sigma_i \). From the premise of Rule 19, if we name \( B'' = B \cup (\emptyset_N, \emptyset_D, R') \), we have \([\mu_i / s'_i](\mu''')_i ; \sigma'''' \Rightarrow ; B'' \vdash M'_s : \bullet ; r'''' \Rightarrow \sigma'''' \). But from Rule 26, if we let \( R''' = \{ s'_i \mapsto r'''' \} \) and \( B''' = B \cup (\Delta', \emptyset_N, D', R''') \), we also have \( \mu'''; \sigma'''' \Rightarrow ; B''' \vdash M'_s : \bullet ; \bullet \Rightarrow \sigma''''' \). Because \( \vdash (M'_s, r''') \Rightarrow \mu'''; \sigma''''' \), so from Lemma 3.10, we have \( \Delta \vdash [\mu_i / s'_i](\mu''')_i \equiv \mu'''; \sigma''''' \), which also implies \( \Delta \vdash \mu'' : \kappa'' \). At the same time, we can see \( B''' \) is related to \( B'' \) via a TGC substitution \([\mu_i / s'_i] \), thus from Lemma 3.11, we can deduce \( \Delta \vdash [\mu_i / s'_i](\sigma''') \equiv \sigma_i \); thus \( \Delta \vdash [\mu_i / s'_i](\sigma'''' \Rightarrow \sigma''''' \equiv \sigma_i \), because \( f_i \) has type \( \forall s'_i :: \kappa_i; \sigma'''' \Rightarrow \sigma''''' \), and \( s_i \) has type \( \sigma_i \), so \( \Delta; \Gamma \vdash @(f_i[\mu])s_i : \sigma'_i \).

In the case of \( r_f = (A_1, \text{aux}) \), the auxiliary information \( A_1 \) must be of form \((\lambda s'_i :: \kappa_i; \mu_i''', \forall s'_i :: \kappa_i; \sigma'_i''') \Rightarrow \sigma'_i'''') \); furthermore, such functor realization must be introduced by Rule 18 in Figure 11; so if we let \( \Delta' = \{ s'_i :: \kappa_i \} \) and \( s'_i ; s'_i ; B \cup (\Delta', \emptyset_N, \emptyset_D, \emptyset_n) \vdash M_s : N''' ; r''''' \Rightarrow \sigma''''' \), then from Lemma 3.12 and Lemma 3.10, we can deduce that \( B \vdash [\mu_i / s'_i](\sigma''') \equiv \sigma_i \). Next, let \( R'''' = \{ s'_i \mapsto r'''' \} \) and \( B'''' = B \cup (\Delta', N''', D', R''') \), then from Rule 18, we have \( B'''' \vdash m'_i : \bullet ; M'_s ; r'''' \Rightarrow \bullet \) and \( \vdash (M'_s, r''') \Rightarrow \mu'''; \sigma''''' \). But from the premise of Rule 19, if we name \( B''' = (\Delta, \text{Not} B, \text{Do} B'' \cup D', \text{Ro} B' \cup R') \), we should also have \( B''' \vdash m'_i ; N''' ; \bullet ; r'''' \Rightarrow \bullet \). Because \( B'''' \) is related to \( B''' \) via a TGC substitution \([\mu_i / s'_i] \) and \( \vdash (M'_s, r''') \Rightarrow \mu'''; \sigma''''' \), we can deduce from Lemma 3.13 that \( \Delta \vdash [\mu_i / s'_i](\mu''')_i \equiv \mu'''; \sigma''''' \). Therefore, we prove \( \Delta \vdash \mu'' : \kappa'' \) and \( \Delta; \Gamma \vdash @(f_i[\mu])s_i : \sigma'_i \). □

3.4 Examples

To get a better understanding about our algorithm, we show how our translation procedure works on several sample NRC programs. In the following, we try to use the ML syntax whenever possible (instead of the NRC syntax) to simplify the presentation. We omit the part of every NRC identifier by always choosing unique identifier names. We also use ML-like signature declaration as syntactic sugars (keyword \texttt{funsig} denotes functor signatures). Our first example is a simple higher-order functor declaration:

\begin{verbatim}
signature ASIG = sig type t end
funsig FSIG = fsig (A : ASIG) : sig type u = A.t end
signature XSIG = sig functor F : FSIG end

functor G (X : XSIG) = struct structure I = struct type t = int end
  structure J = (I : ASIG)
  structure K = X.F(J)
end.
\end{verbatim}

Here, identifiers \texttt{ASIG}, \texttt{FSIG}, and \texttt{XSIG} behave like macros and they are inlined whenever used inside any NRC program. Inside the functor body, structure \texttt{I} has signature

\begin{verbatim}
sig type t = int end,
\end{verbatim}
this is not same as the parameter signature of \( \mathbf{X}, \mathbf{F} \) so we need to insert an explicit signature matching to create structure \( \mathbf{J} \). To show how our algorithm works, we give the detailed translation results of every module expression in Figure 12. Here, for every functor parameter \( Z \) (e.g., \( \mathbf{X} \) and \( \mathbf{A} \) in the example), we use \( Z_T \) to denote its corresponding TGC constructor identifier and \( Z_v \) to denote the TGC value identifier; if \( Z \) has signature \( ZSIG \), we can infer the TGC kind of \( Z_T \) (denoted as \( \kappa_Z \)) and the TGC type of \( Z_V \) (denoted as \( \sigma_Z \)). Similarly, for every module identifier \( Z \), we give its corresponding TGC type constructor (denoted as \( \mu_Z \)) and target term expression (denoted as \( \epsilon_Z \)). Notice the type part for the body of functor \( \mathbf{X}, \mathbf{F} \) does not include type \( \mathbf{B} \). Doing so would force the use of dependent kinds to model \( \kappa_X \). The fact that type \( \mathbf{t} \) in structure \( \mathbf{K} \) is equivalent to \( \text{int} \) is deduced and propagated by the elaborator.

Although value components are not included in the NRC calculus, they can be handled easily (see Section 5.1 for more details). In our second example, we show how our algorithm would work on programs that contain value components; we use the example referred earlier in the Introduction section (see Figure 1).

```plaintext
signature ASIG = sig type s val f : s end
fnsig FSIG = fsig (X : ASIG) : ASIG
signature BSIG = sig functor F : FSIG end

structure SA : ASIG = struct type s = int val f = 3 end
structure SB = struct functor F (X : ASIG) : ASIG = struct type s = X.s -> X.s
                             fun f (z : X.s) = X.f end
functor APP (B : BSIG) : ASIG = B.F(SA)
structure SC = APP(SB)
```

Here, to simplify the presentation, we did not transform the functor body of \( \text{APP} \) into a definitional structure \((m_b)\); doing so is straightforward because all we need is to enclose the current body inside an additional \textbf{struct} ... end layer. The result of the translation is shown in Figure 13. To avoid the notation confusion, a TGC type of form \( T(\mu_t) \) is simply represented as \( \mu_t \).
4 Cross-module program analysis

We can extend the stamp-based semantics for NRC to support cross-module program analysis. Full transparency guarantees that type information be optimally propagated across module boundaries. We could propagate other static information in the same manner, and by doing this, many static program analyses for the core languages can be extended to work across higher-order modules. Because the realization part of a modtype is always hidden inside the compiler, we can freely add new static information into the realization without making any changes to the source-level signature calculus.

To support cross-module inlining, we add a new form of the "type" specifications and declarations into the NRC calculus. We call it \textit{binfo}, meaning the binding information:

\begin{align*}
\text{spec} & \quad D ::= \ldots \mid \text{binfo} \; b_i \\
\text{decl} & \quad d ::= \ldots \mid \text{binfo} \; b_i = e_b
\end{align*}

where \(e_b\) is a form of \textit{binfo} expressions, possibly defined as follows:

\begin{align*}
\text{bexp} & \quad e_b ::= p_b \mid \text{Dyn} \mid \text{STFun}(e_i) \mid \text{STVal}(c) \mid \ldots
\end{align*}

Here, \textit{Dyn} denotes a value that we know nothing about at compile time; \textit{STFun} (\textit{e}) denotes a function that is statically known as a \textit{closed} expression \textit{e}, written in some typed intermediate language such as TGC; and \textit{STVal} (\textit{c}) refers to a statically known constant \textit{c}. Notice we do not make any changes to SFC, instead, the SFC-to-NRC translation can use heuristics (or hints from the programmer) to decide the possible inlining candidates, and then insert the proper \textit{binfo} specifications and declarations into the NRC code.

We extend the semantic objects, NRC realizations, to include a mapping from binfo identifiers to their corresponding binding information. The \textit{binfo} expressions will be recorded in the realization closure of a functor, just like normal type declarations. All deduction rules remain unchanged, and the binding information will be optimally propagated just as the normal type information.
We then systematically replace each value specification in signatures by a compound structure specification that records all the relevant type, value, and binfo information. Taking the code in Figure 1 as our example, the value specification val f : s in ASIG is re-interpreted internally as follows:

```plaintext
structure f : sig val dv : s
  binfo dvB
  type tenv
  type venvT
  val venv : venvT
  binfo venvB
end
```

Here, binfo vₜ is a new form of specification used for binding information. Signature matching on binfo is always transparent. The value component dv is f's original definition. The binfo component dvB denotes f's binding information. We use tenv and venv to record all the free type and value identifiers (and paths) in the definition of f. We use venvT to specify the type of venv because each value component must have a type. Finally, the closure venv might be a constant itself, so we introduce venvB to record its binding information. Given a structure S with signature ASIG, the access to S.f can now be implemented as follows: (1) if dvB is Dyn, or if the optimization is turned off, then S.f under the new interpretation is just S.f.dv; (2) if dvB is STFun (e), then S.f is translated into "® (e[S.f.tenv]) venv" where venv is c if venvB is STVal (c), or S.f.venv if otherwise; (3) if dvB is STVal (c), then S.f is simply c.

Inside each structure body, we replace each value component by a structure declaration that is consistent with our changes on the signatures. For example, function f inside structure SB.F is replaced by the following:

```plaintext
structure f = struct fun dv (x : X.s) = X.f
  binfo dvB = STFun (Lₜ = Ω λvₑ : tₑ. λx : tₑ, vₑ)
  type tenv = X.s
  type venvT = X.s
  val venv = X.f.dv
  binfo venvB = X.f.dvB
end
```

If we use the same stamp-based semantics to elaborate the functor application APP(SB), we can deduce that the f component in structure SC (in Figure 1) is simply "λx :: int.3".

Under this algorithm, the binding information of each value component is always propagated optimally even across higher-order modules. A more traditional approach would compile the higher-order modules into the usual higher-order functions in the core language, and then perform the heavy-weight control flow analysis [Shi91] on them. Our module elaboration algorithm is somewhat similar to the abstract execution, but it separates the module-level declarations from the the core-language expressions within. The elaboration is simple and very efficient because the module-level code is always small and non-recursive.

5 Implementation

We have implemented both the translation algorithm and the cross-module inlining algorithm in the SML/NJ compiler [SA95] and the FLINT/ML compiler [Sha97b]. The implementation in SML/NJ has been released and in production use since version 109.24 (January 9, 1997). In our implementation, we extended the NRC-to-TGC translation to handle other features in SML'97 [MTHM97] such as value components, opaque signature
matching, polymorphic types, and recursive datatypes. The translation makes it possible to support type-based optimizations even in the presence of higher-order modules. The cross-module inlining algorithm we implemented currently only inlines and specializes all the primitive functions, but the binding information is fully propagated across the signature matching and functor application. The new inlining algorithm replaced the old ad-hoc algorithm in SML/NJ which does not even propagate inlining information across signature matching. In this section, we explain how we handle other features in SML'97 and how our techniques interact with separate compilation.

5.1 Value components

Adding value components (e.g., the val keyword in ML) to the NRC calculus is quite trivial. Both the semantics and the translation are already equipped with the necessary utility functions to support value specifications and value declarations. Handling value specifications in signatures requires a utility function (i.e., c2m) to convert source-level types (\(\mu_c\)) into internal semantic types (\(\mu_m\)). Similarly, to infer the full signature of an arbitrary structure expression, we use a utility function (i.e., m2c) to convert the semantic type (\(\mu_m\)) of each value component back to its source-level counterpart (\(\mu_c\))—this is possible because the stamp environment (\(N\)) in the basis maintains a one-to-one mapping from each type stamp to its definitional type path.

5.2 Functor application

The static semantics given in Section 3.2 always re-elaborates the functor body at each functor application, but much of the work is redundant. For example, given a functor definition \(F\) inside the body of another functor \(G\), each time functor \(G\) is applied, the body of \(G\) thus also the definition of \(F\) must be re-elaborated; according to Rule 18 in Figure 9, elaborating the definition of \(F\) always require re-elaborating the body of \(F\), but this is unnecessary. Our implementation tries very hard to eliminate all such redundant elaborations.

Value components are also elaborated once and for all at functor definition. More specifically, at each functor application, we do not redo the type-checking of value declarations inside the functor body. Instead, we infer the types of all value components and use the realization environment to propagate type identities. Functor application under our semantics involves re-elaborating the type-related components only.

5.3 Opaque signature matching

The translation algorithm presented in Section 3.3 assumes that signature matching is done transparently. However, opaque signature matching [MTHM97] can be supported quite easily as well by using the same signature-instantiation algorithm presented in Figure 10.

All flexible type components are turned into “abstract” types, represented as fresh stamps annotated with its representation type (e.g., \(n(\kappa, \mu)\)). Opaque matching creates a structure where all flexible type components are turned into “abstract” types. For example, in the following ML code:

```ml
structure AA := sig type s val f : s end = struct type s = real val f = 3.0 end
```

the s component in the resulting structure AA is a new abstract type. In our stamp-based semantics, s will be assigned a new unique type stamp. We also memorize the actual type information for each abstract type, so s will be represented as \(n(\Omega, \mu)\) where \(n\) is the new stamp, \(\Omega\) is the kind, and \(\mu = \text{real}\) is the representation
type. This allows the compiler to support type-based manipulations (e.g., representation analysis, pickling, debugging) even on abstract values (e.g., $\mathbb{A}\cdot f$).

The NRC-to-TGC translation converts all stamped types in NRC into concrete TGC types by dropping all the stamps. This is sufficient if the underlying application does not analyze on abstract types themselves. However, more future work is required if we want to propagate abstract types into the intermediate language (e.g., the $F_\omega$ calculus must be extended to support abstract types).

### 5.4 Polymorphic types

Polymorphic functions introduce a small technical problem when propagating the value binding information across the module boundaries. Signature matching may constrain a value of polymorphic type $\sigma$ into one with a more specific type $\sigma'$ where $\sigma'$ is an instance of $\sigma$. We solve this problem by always propagating both the value binding information and the original type at its definition site. We can then ignore the change of types during signature matching. Whenever we need to use the binfo, we insert proper wrapper code to coerce it from the original definition type to the new client type.

### 5.5 Concrete datatypes

Type generativity for datatype declarations can be easily incorporated into our stamp-based semantics. All we need is to generate a new type stamp every time we process a datatype declaration. For the NRC-to-TGC translation, we treat datatype specification as simple type abbreviation; stamps created for datatype declaration are ignored by the translation. This won’t be a problem as long as the underlying compiler use same representations for structurally equivalent datatypes.

### 5.6 Sharing constraints

In Section 3, we have assumed that the SFC-to-NRC translation can convert all sharing constraints into type abbreviations. This is not always possible inside the SML'97 language. If datatype specifications are allowed in signatures. For example, in the following signature,

```
signature XSIG = sig type s
    type u = s -> s
    datatype t = A of s * u
    sharing type s = t
end
```

type sharing between $s$ and $t$ cannot be lifted to the specification site for $s$ as it leads to mutually recursive type definitions. Our implementation does not eliminate such type sharing, instead, we use a more sophisticated signature instantiation algorithm to calculate the set of flexible type components in a signature.

### 5.7 Relationship to separate compilation

Several recent papers [Ler94, HL94] argued that the SML'90 module language [MTH90] provides poor support to Modula-2-like true separate compilation, especially under those scenarios described by Cardelli [Car97]. The new SML'97 module language fixed some of these problems by supporting opaque signature matching and type
abbreviations in signatures. Still, an SML'97 program fragment cannot be closed over all of its free functor variables since modules in SML'97 does not allow parameterization over other functors.

Adding higher-order modules to SML'97 would provide better support to separate compilation, but it still does not support true separate compilation. This is because the signature expression used in the NRC calculus is not expressive enough to capture all internal typing properties of a module. As a result, arbitrary modules cannot be abstracted over because they do not always possess a syntactic signature. For example, in the following ML code,

```ml
signature SIG = sig type t end
functor FAPP(B: sig functor F(X: SIG) : SIG
   structure A: SIG
   end) = B.F(A)
structure R = struct structure R1 = FAPP(struct functor F(X: SIG) = X
   structure A : SIG = struct type t=int end
   end)
structure R2 = FAPP(struct functor F(X: SIG) = struct type t=int end
   structure A : SIG = struct type t=bool end
   end)

it is impossible to turn R into a functor parameterized by FAPP and still obtain that the components R1.t and R2.t are both equal to int.

Nevertheless, fully transparent higher-order modules does make it easier to support Cardelli [Car97]'s scenarios. Consider the following example: a programmer decides to write a large piece of ML software; he first writes down the interfaces for several of his modules, say, SIG1 and SIG2 for structure S1 and S2, FSIG1 and FSIG2 for functor F1 and F2; then he decides to write the actual implementation code for a module named S3. Let's assume that his code for S3 may refer to all the previous modules such as S1, S2, F1 and F2, can he compile S3 without even implementing the other four modules?

He can decide what he really wants to convey using either transparent and opaque signatures. Suppose SIG1 is defined as follows:

```ml
signature SIG1 = sig type t val f : t -> t end
```

If he marks SIG1 as opaque, then he is assuming that t will be abstract to the rest of the modules. But he could mark SIG1 as transparent, which could mean that he doesn't care about the actual definition of t or simply that t could be anything.

In both cases, the compiler can simply implement S3 as an higher-order functor taking all four modules as its arguments. Later when the implementations of these four modules become available, the linker applies the functor to these modules, producing an implementation for the real S3.

One nice thing about our typed cross-module compilation framework is that we do not lose any static binding information exported by S3. The full-transparency property guarantees that however the implementation of the other four modules are like, the linker will always be able to recover the same set of value binding information as if S3 is compiled as a structure knowing the actual implementations of the other four modules.
5.8 Miscellaneous

Although the translation algorithm itself does not improve the efficiency of the module code, it does allow many type-based optimizations to be applied to languages that use ML-style modules. Recent work [Sha97a] shows that type-based optimizations can dramatically improve the performance of heavily modularized ML programs.

Another issue is on how to make the implementation of our translation algorithm efficient and scalable. Because the translation makes heavy use of large modtype information, a naive implementation can easily add exponential overhead to the compilation and execution of a program. In a companion paper [SLM98], we present a series of techniques on how to optimize the time and space costs of representing and manipulating large types; we show that our translation algorithm can be implemented with minimum overhead.

6 Related work

Module systems have been an active research area in the past decade. The ML module system was first proposed by MacQueen [Mac86] and later incorporated into Standard ML [MTH90]. Harper and Mitchell [HM93] show that the SML’90 module language can be translated into a typed lambda calculus (XML) with dependent types. Together with Moggi, they later show that even in the presence of dependent types, type-checking of XML is still decidable [HMM90], thanks to the phase-distinction property of ML-style modules. The SML’90 module language, however, contains several major problems; for example, type abbreviations are not allowed in signatures, opaque signature matching is not supported, and modules are first-order only. These problems were heavily researched [HL94, Ler94, Ler95, Lil97, Tof92, MT94, Jon96] and mostly resolved in SML’97 [MTH97].

The main remaining issue is with the design of higher-order modules, with proposals ranging from fully transparent ones [MT94], to applicative functors [Ler95, Cou97], or abstract functors [HL94, Ler94, Lil97]. Fully transparent modules are most expressive, but it is not clear whether they are absolutely necessary; they also interact poorly with true separate compilation [Ler94]. This paper shows that at least from the implementation point of view, full transparency is important in providing optimal support to efficient cross-module compilation.

The question of whether higher-order modules can be compiled into simple $F_{\omega}$-like calculus has been open for a while. Several recent papers [HMM90, Bis95, Ler95] have attacked variants of this problem with different motivations; however, they all impose severe restrictions to their module languages. The algorithm hidden inside Harper, Mitchell, and Moggi’s phase-distinction paper [HMM90] is most related, however, it does not support type abbreviation and sharing in signatures.\footnote{Although the paper by Harper et al [HMM90] was published in 1990, the importance of its phase-splitting algorithm was not recognized until very recently. In fact, we reinvented the same algorithm while working on the type-directed compilation of ML-style modules during 1996. The first version of our algorithm was presented at the IFIP WG2.8 meeting in September 1996. It was at that meeting when Bob Harper pointed us to the phase-distinction paper. In January 1997, Greg Morrisett [Mor97] told us that he had problems adapting the original phase-splitting algorithm [HMM90] to SML [MTH97] since it does not support type abbreviations in signatures. As a result, the TIL compiler today is still using an intermediate language with dependent “singleton” kinds rather than the plain $F_{\omega}$ calculus.}

Supporting type abbreviation is non-trivial, as discovered by Morrisett [Mor97] and also demonstrated in this paper. Harper and Stone [HS97] give a new type-theoretical semantics for the entire SML’97, however, their internal language, IL, contains a separate module calculus that uses translucent signatures. Biswas [Bis95] gives a semantics for the MacQueen-Tofte modules based on simple polymorphic types; however, his algorithm does not support parameterized type constructors. Another difference is that in his scheme, functors are not considered as higher-order type constructors, instead, he has to encode certain type constructors of kind $\Omega$ using higher-order types; this significantly complicates his semantics. Finally, Leroy [Ler95] uses applicative functors to achieve full transparency, but his approach handles limited
functor arguments only; Courant [Cou97]'s semantics does not have such restriction, but he did not give a translation of his calculus into the $F_\omega$ calculus.

Our static semantics for higher-order modules is based on the the same stamp-based approach used in the official definitions for SML’90 [MTH90, MT91] and SML’97 [MTHM97]. The stamp-based semantics uses a global name set to model type generativity and type abstraction: a new type is represented as a fresh stamp not used in the current name set. The operational nature of this approach makes it good for efficient implementations but harder for formal reasonings. A more type-theoretic approach is to use existential types or manifest types to module type abstraction [Ler94, HL94]. However, none of the existing type-theoretic approaches have been able to model the full-transparency property in the MacQueen-Tofte system.

Both Lillibrige [Lil97] and Leroy [Ler96a] discussed how to add value identities to their module interfaces though neither of them gave any actual algorithm. Blume and Appel [BA97] proposed a cross-module inlining algorithm that supports inlining of functions with free variables. Their algorithm is carried in an untyped setting, so type specialization is not directly supported; neither does their algorithm guarantee the fully transparent propagation of the inlining information. Our algorithm does guarantee the optimal propagation, but at the price of further complicating the module elaboration. We are currently working together on an inlining algorithm that combines the best of both schemes.

Type-directed compilation has received much attention lately, but little has been done to extend it to work across higher-order modules. Shao and Appel [SA95] extended Leroy’s representation analysis [Ler92] to work for the SML’90 modules; their algorithm works only for the pure-coercion-based representation analysis [Ler92]. The algorithm in this paper translates the module language into the $F_\omega$ calculus, so type-based optimizations [Ler92, Sha97a, HM95, MMH96, Tol94] that work for $F_\omega$ immediately work for higher-order modules as well.

7 Conclusions

We have presented a series of techniques for compiling across higher-order modules. These techniques have been implemented and released with the SML/NJ compiler since version 109.24 (January 9, 1997). The main contribution of our work is the translation algorithm from ML-style modules (SML’97 extended with MacQueen-Tofte higher-order modules) to the $F_\omega$ calculus. Without such translation, none of those important type-based optimizations [HM95, Sha97a, Sha97b] would apply to the full SML language. We have also presented ways to extend various program analyses to work across higher-order modules; in fact, we show that for fully transparent modules, static information can always be optimally propagated across the module boundaries. Finally, we have presented a new and more complete formal definition for the MacQueen-Tofte higher-order modules; our new semantics covers a much richer language and solves all the remaining technical problems in MacQueen and Tofte’s original proposal [MT94].

Availability

The implementation discussed in this paper is now released with the Standard ML of New Jersey (SML/NJ) compiler and the FLINT/ML compiler [Sha97b]. SML/NJ is a joint work by Lucent, Princeton, Yale and AT&T. FLINT is a modern compiler infrastructure developed at Yale University. Both FLINT and SML/NJ are available from the following web site:

http://flint.cs.yale.edu
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References


A  Static semantics for TGC

The typing rules for the F_n-based TGC calculus are given in Figure 14. The rules for constructor equivalence and type equivalence should also include the the standard rules for equivalence and congruence (omitted in Figure 14 for brevity). The equivalence relation for constructors is consistent with the standard notion of reductions in a simply-typed lambda calculus extended with products, so we can easily see that the constructor calculus is strongly normalizing and every TGC constructor has a unique normal form under the defined equivalence. Finally, the typing rules for terms and declarations are also standard as in the usual polymorphic lambda calculus [Gir72, Rey74, HM93].

B  SFC and the SFC-to-NRC translation

The surface module calculus SFC is a subset of SML'97 extended with the MacQueen-Tofte higher-order modules [MT94]. The syntax of SFC is defined in Figure 15. Here, each SFC program consists of a sequence of declarations (d). Symbol t, s, and f denote type, structure, and functor identifiers; p_t, p_s, and p_f are access paths for the type, structure, and functor components in a structure. The SFC calculus includes standard constructs such as signatures (M_s), functor signatures (M_f), structure expressions (m_s), and functor expressions (m_f). Unlike NRC, SFC also supports sharing specification, arbitrary functor body, let structure, and more flexible signature subsumption.

To translate from SFC to NRC, we perform a series of syntactic transformations and normalizations on SFC. First, we eliminate the type-sharing constraints by converting them into type abbreviations [Ler96b]. Intuitively, a sharing specification can be pushed through a sequence of other specifications until it hits the root identifier involved in the constraints. For example, a specification such as

\[
\text{type } t :: \kappa_c \text{ sharing type } t = p_t
\]

can be rewritten as a type abbreviation:

\[
\text{type } t :: \kappa_c = p_t.
\]

Similarly, a specification such as \texttt{structure } s : \texttt{sig} D \texttt{ end sharing type } p_h = p_h \texttt{ can push the sharing constraint inside to } D \texttt{ if the root identifier of } p_h \texttt{ is same as } s. \texttt{Leroy} [Ler96b] gave a detailed algorithm for this procedure.

Next, we convert all SFC expressions into \textit{A-normal form} [FSDF93]: functor application must be applying a functor identifier (e.g., f) to a structure identifier (e.g., s) only; signature matching is only performed on structure identifiers as well. For example, functor application \( m_f(m_s) \) can be rewritten as

\[
\text{functor application}
\]
Constructor formation and constructor equivalence:

\[ \Delta \vdash \alpha :: \kappa_i \Rightarrow \alpha :: \kappa_i \quad (\text{cvar}) \]
\[ \Delta \vdash \text{Int} :: \Omega \quad (\text{cint}) \]
\[ \Delta \vdash \mu_i :: \Omega \quad \Delta \vdash \mu'_i :: \Omega \]
\[ \Delta \vdash \mu_i \rightarrow \mu'_i :: \Omega \quad \text{(capp)} \]
\[ \Delta \vdash \lambda \alpha :: \kappa_i.\mu_i :: \kappa_i \rightarrow \kappa'_i \quad \text{(cfn)} \]
\[ \Delta \vdash \mu_i :: \kappa_i \rightarrow \kappa'_i \quad \Delta \vdash \mu'_i :: \kappa_i \]
\[ \Delta \vdash \{l = \mu_i, \ldots, l' = \mu'_i\} :: \{l :: \kappa_i, \ldots, l' :: \kappa'_i\} \quad \text{(cprod)} \]
\[ \Delta \vdash \{\ldots,l :: \kappa_i, \ldots\} :: \{\ldots,l' :: \kappa'_i\} \quad \text{(cselect)} \]

Type formation and type equivalence:

\[ \Delta \vdash \sigma_i \quad \Delta \vdash \sigma_i' \Rightarrow \sigma_i' \quad (\text{tarw}) \]
\[ \Delta \vdash \alpha :: \kappa_i \Rightarrow \sigma_i \quad \Delta \vdash \forall \alpha :: \kappa_i.\sigma_i \quad (\text{tpoly}) \]
\[ \Delta \vdash \sigma_i \quad \ldots \quad \Delta \vdash \sigma'_i \quad \text{(tprod)} \]
\[ \Delta \vdash T(\mu_i) :: \Omega \quad \Delta \vdash T(\mu'_i) :: \Omega \quad \text{(tar'}-\text{eqv)} \]

Term formation and declaration formation:

\[ \Delta; \Gamma \vdash i :: T(\text{Int}) \quad \text{(int)} \]
\[ \Delta; \Gamma \vdash x :: \Gamma(x) \quad \text{(var)} \]
\[ \Delta; \Gamma \vdash e_i :: \sigma_i \quad \text{(let)} \]
\[ \Delta; \Gamma \vdash \lambda x :: \sigma_e.e_i :: \sigma_i \rightarrow \sigma'_i \quad \text{(fn)} \]
\[ \Delta; \Gamma \vdash e_i :: \sigma_i \rightarrow \sigma'_i \quad \Delta; \Gamma \vdash e'_i :: \sigma'_i \quad \text{(app)} \]
\[ \Delta; \Gamma \vdash \lambda \alpha :: \kappa_i.e_i :: \forall \alpha :: \kappa_i.\sigma_i \quad \text{(tfn)} \]
\[ \Delta; \Gamma \vdash e_i :: \forall \alpha :: \kappa_i.\sigma_i \rightarrow \mu_i :: \kappa_i \quad \text{(tapp)} \]
\[ \Delta; \Gamma \vdash \{l = e_i, \ldots, l' = e'_i\} :: \{l :: \sigma_i, \ldots, l' :: \sigma'_i\} \quad \text{(prod)} \]
\[ \Delta; \Gamma \vdash e_i :: \sigma_i \quad \ldots \quad \Delta; \Gamma \vdash e'_i :: \sigma'_i \quad \text{(select)} \]
\[ \Delta; \Gamma \vdash \varepsilon :: \emptyset_i \quad \text{(edec)} \]
\[ \Delta; \Gamma \vdash d_i :: \Gamma \quad \Delta; \Gamma \vdash \{x :: \sigma_i\} :: d_i :: \Gamma' \quad \text{(sdec)} \]

Figure 14: Static semantics for TGC
Access paths:

\[
\begin{align*}
\text{strpath} & \quad \mathit{p}_s \quad ::= \quad s \mid \mathit{p}_s.s \\
\text{fctpath} & \quad \mathit{p}_f \quad ::= \quad f \mid \mathit{p}_s.f \\
\text{typpath} & \quad \mathit{p}_t \quad ::= \quad t \mid \mathit{p}_s.t
\end{align*}
\]

Signatures and specifications:

\[
\begin{align*}
\text{spec} & \quad D \quad ::= \quad \varepsilon \mid DD' \\
& \quad \mid \quad \text{type} \quad t :: \kappa_c \\
& \quad \mid \quad \text{type} \quad t :: \kappa_c = \mu_c \\
& \quad \mid \quad \text{structure} \quad s : M_s \\
& \quad \mid \quad \text{functor} \quad f : M_f \\
& \quad \mid \quad D \text{ sharing type} \quad \mathit{p}_t = \mathit{p}'_t \\
\text{sig} & \quad M_s \quad ::= \quad \text{sig} \ D \text{ end} \\
\text{fsg} & \quad M_f \quad ::= \quad \text{fsg}(s:M_s)M'_s
\end{align*}
\]

Kinds and types:

\[
\begin{align*}
\text{kind} & \quad \kappa_c \quad ::= \quad \Omega \mid \Omega \rightarrow \kappa_c \\
\text{tycon} & \quad \mu_c \quad ::= \quad \mathit{p}_t \mid \mathit{int} \mid \mu_c \rightarrow \mu'_c \\
& \quad \mid \quad \lambda t :: \Omega , \mu_c \mid \mu_c[\mu'_c]
\end{align*}
\]

Modules and declarations:

\[
\begin{align*}
\text{decl} & \quad d \quad ::= \quad \varepsilon \mid dd' \mid \text{local} \ d \ \text{in} \ d' \ \text{end} \\
& \quad \mid \quad \text{type} \quad t :: \kappa_c = \mu_c \\
& \quad \mid \quad \text{structure} \quad s = m_s \\
& \quad \mid \quad \text{functor} \quad f = \mathit{mf} \\
\text{str} & \quad m_s \quad ::= \quad \mathit{ps} \mid \mathit{mf}(m_s) \mid (m_s : M_s) \\
\text{struct} & \quad d \quad ::= \quad \text{let} \ d \ \text{in} \ m_s \ \text{end} \\
\text{fct} & \quad \mathit{mf} \quad ::= \quad \mathit{pf} \ \mid \ \text{fuct} \ (s : M_s)m_s
\end{align*}
\]

Figure 15: Syntax of the surface module calculus SFC

This procedure is recursively applied to all SFC sub-expressions.

Third, in order to avoid name captures, we attach a unique internal name to each SFC identifier; we also make sure that all functor definitions and functor signatures have uniquely named formal parameters. More specifically, each time we bind an identifier \( x \), we generate a new stamp \( i \) and rename all the uses of this \( x \) into \( x_i \). For example, the following program (assume it is already A-normalized):

\[
\text{structure} \ s = \\
\text{let \ structure} \ u = \text{struct \ type} \ t = \text{int} \quad \text{type} \ x = t \ \text{end} \\
\text{in} \ (u : \text{sig \ type} \ t \ \text{end}) \\
\text{end}
\]

is rewritten into:

\[
\text{structure} \ s_i = \\
\text{let \ structure} \ u_j = \text{struct \ type} \ t_k = \text{int} \quad \text{type} \ x_m = t_k \ \text{end} \\
\text{in} \ (u_j : \text{sig \ type} \ t_i \ \text{end}) \\
\text{end}
\]

where the \( t \) component of structure \( s \) is now referenced as \( s_i . t_i \) (but not \( s_i . t_k \)). This renaming scheme creates a name mismatch for some signature-matching expressions (e.g., between the \( t_k \) of \( u_j \) and \( t_i \) in the signature). We fix this by introducing an auxiliary structure definition \( u_m \):
structure $s_i =$
let structure $u_j =$ struct type $t_h =$ int type $x_m =$ $t_h$ end
structure $u_n =$ struct type $t_l =$ $u_j.t_h$ end
in ($u_n :$ sig type $t_l$ end end

The renaming algorithm can be implemented by maintaining an environment that maps every type identifier into one with proper internal stamp, every structure (or functor) identifier into a signature (or functor signature) whose components have already been properly stamped. Every access path $p_a$ can then be renamed by a simple environment lookup.

Along with the renaming procedure, we also make concrete the enrichment coercions occurred at every signature matching—including those performed on the argument and result of each functor application. This is reasonable because we often have to create a new structure such as $u_n$ anyway to eliminate name mismatches; for example, the $x$ component in the above structure $u_j$ is dropped in $u_n$. This procedure is recursively performed on all components; for instance, matching a functor $\text{functor } f = \text{funct}(s : M_s)m_s$ against a functor signature $fsig(s' : M'_s)M''_s$ will result in the following coercion:

\[
\text{functor } f'(s' : M'_s) = \\
\text{let structure } a = (s' : M_s) \\
\text{structure } r = f(a) \\
\text{structure } c = (r : M''_s) \\
in c
\]

end

After this transformation, signature matching such as $(s_i : M_s)$ always satisfies the following invariants: structure $s_i$ contains the same number of components as those in $M_s$; each pair of corresponding components have same identifiers and stamps (so they are ordered in the same way); furthermore, each functor component in $s_i$ must have a signature syntactically equivalent to its counterpart in $M_s$.

Fourth, we convert the functor body into a definitional structure expression of form $\text{struct...end}$. Given a functor expression $\text{funct}(s_i : M_s)m_s$, we wrap an extra layer around the functor body $m_s$ into:

\[
\text{funct } (s_i : M_s) \text{ struct structure } R = m_s \text{ end.}
\]

Functor body in functor signatures is transformed in the same way. Meanwhile, functor application such as $F(S)$ is translated into:

\[
\text{let structure } T = F(S) \text{ in } T.R \text{ end.}
\]

Finally, we lift out all module declarations in the let expressions and turn them into local declarations. This is always possible if we assume an SFC program is just a set of module declarations. Each declaration inside the module expressions can be lifted upwards until one of the following happens: (1) it reaches the top of a functor body, but after previous transformations, all functor body is of form $\text{struct } d \text{ end}$; or (2) it reaches the top-level declaration $d$ of a program. In both cases, we can convert let declarations (say $d'$) inside $d$ into local declarations by simply attaching them to the front of $d$ as in $\text{local } d'$ in $d$ end.