CS 428/528 Lecture 15: The P Framework for Communicating State Machines

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Based on the PLDI13 paper by Desai et al

Communicating State Machines



P Architecture





P Examples







(b) Door ghost machine

ConsiderStopping						
Deferred: StartTimer						
Action:						
if * then						
<pre>if * then send(Elevator, OperationFailure);</pre>						



Figure 1: Elevator example

P Language Syntax

program	::=	evdecl machine $+ m(init^*)$	stmt	::=	skip
machine	::=	optghost machine m			$x := \exp r$
		vrdecl* actdecl*			$x := \mathbf{new} \ m(init^*)$
		spdecl [*] cldecl [*] acdecl [*]			delete
					send(expr, e, expr)
optghost	::=	$\epsilon \mid \mathbf{ghost}$			$\mathbf{raise}(e, expr)$
evdecl	::=	$event edecl^+$			leave
vrdecl	::=	optghost ${f var}$ vdecl $^+$			return
actdecl	::=	$action (a, stmt)^+$			$\mathbf{assert}(expr)$
stdecl	::=	state $(n, \{e_1, e_2, \dots, e_k\}, stmt, stmt)^+$			stmt; stmt
spdecl	::=	$step(n,e,n)^+$			if expr then stmt else stmt
cldecl	::=	$\operatorname{call}(n,e,n)^+$			while expr stmt
acdecl	::=	$\mathbf{act}(n, e, a)^+$	init	::=	$x = \exp r$
edecl	::=	e(type)	expr	::=	$\mathbf{this} \mid \mathbf{msg} \mid \mathbf{arg} \mid b \mid c \mid \perp \mid x \mid *$
vdecl	::=	x:type			uop expr expr bop expr
			- • · ·		
type	::=	void bool int event id	$c \in \operatorname{int}$		$b \in bool$
			$\neg, - \in uop$		$+, -, \land, \lor \in bop$
			$r\in expr$		$a,e,m,x\inname$

configuration. A machine configuration corresponding to identifier *id* is of the form (γ, σ, s, q) with components defined as follows:

- γ is a sequence of pairs (n, α), where n is a state name, and α is map from events to A∪{T, ⊥}, where A is the set of all actions declared in machine Name(id). This sequence functions as a call stack, to implement call and return, and the α values are used to inherit deferred events and actions from caller to callee. For an event e, α(e) can be an action a, or the value T indicating that the event is deferred, or the value ⊥ which indicates that the event does not have an associated action and it is not deferred.
- σ is a map from variables declared in machine Name(id) to their values; this map contains an entry for the local variables **this**, msg and arg.
- *s* is the statement remaining to be executed in machine *id*.
- q is a sequence of pairs of a event-argument pairs representing the input buffer of machine *id*.

state n is executed whenever control leaves n. Given a machine name m and a state n in m, let Deferred(m, n) denote the associated set of deferred events and let Action(m, n, e) be an that action a is associated with event e in state n, if such a binding exists or \bot otherwise. Let Entry(m, n) denote the associated entry statement, and let Exit(m, n) denote the associated exit statement. The initial state of the machine m is the first state in the state list and is denoted by Init(m).

$$\begin{split} \frac{M[id] = (\gamma, \sigma, S[x := r], q) \qquad \sigma(r) \downarrow v}{M \longrightarrow M[id := (\gamma, \sigma[x := v], S[\mathbf{skip}], q)]} \text{ (ASSIGN)} \\ M[id] = (\gamma, \sigma, S[x := \mathbf{new} m'(x_1 = r_1, x_2 = r_2, \dots, x_n = r_n)], q) \\ & id' = fresh(m') \qquad n' = Init(m') \\ \alpha_o = \lambda e. \perp \qquad \sigma(r_1) \downarrow v_1 \qquad \sigma(r_2) \downarrow v_2 \qquad \cdots \qquad \sigma(r_n) \downarrow v_n \\ \sigma' = \lambda x. \perp [\mathbf{this} := id'][x_1 := v_1][x_2 := v_2] \cdots [x_n := v_n] \\ M \longrightarrow M[id := (\gamma, \sigma[x := id'], S[\mathbf{skip}], q)] \\ & [id' := ((n', \alpha_o), \sigma', Entry(m', n'), \epsilon)] \\ \\ \frac{M[id] = (\gamma, \sigma, S[\mathbf{delete}], q)}{M \longrightarrow M[id := \perp]} \text{ (DELETE)} \\ \frac{M[id] = (\gamma, \sigma, S[\mathbf{assert}(r)], q) \qquad \sigma(r) \downarrow \mathbf{true}}{M \longrightarrow M[id := (\gamma, \sigma, S[\mathbf{skip}], q)]} \text{ (ASSERT-PASS)} \\ \frac{M[id] = (\gamma, \sigma, S[\mathbf{skip}; s], q)}{M \longrightarrow M[id := (\gamma, \sigma, S[\mathbf{skip}], q)]} \text{ (SEQ)} \end{split}$$

$$\frac{M[id] = (\gamma, \sigma, S[\mathbf{if} \ r \ \mathbf{then} \ s_1 \ \mathbf{else} \ s_2], q) \qquad \sigma(r) \downarrow \mathbf{true}}{M \longrightarrow M[id := (\gamma, \sigma, S[s_1], q)]} \quad (\text{IF-THEN})$$

$$\frac{M[id] = (\gamma, \sigma, S[\mathbf{if} \ r \ \mathbf{then} \ s_1 \ \mathbf{else} \ s_2], q) \qquad \sigma(r) \downarrow \mathbf{false}}{M \longrightarrow M[id := (\gamma, \sigma, S[s_2], q)]} \quad (\text{IF-ELSE})$$

$$\frac{M[id] = (\gamma, \sigma, S[\mathbf{while} \ r \ s], q) \qquad \sigma(r) \downarrow \mathbf{true}}{M \longrightarrow M[id := (\gamma, \sigma, S[s; \mathbf{while} \ r \ s], q)]} \quad (\text{WHILE-ITERATE})$$

$$\frac{M[id] = (\gamma, \sigma, S[\mathbf{while} \ r \ s], q) \qquad \sigma(r) \downarrow \mathbf{false}}{M \longrightarrow M[id := (\gamma, \sigma, S[s; \mathbf{while} \ r \ s], q)]} \quad (\text{WHILE-ITERATE})$$

$$\frac{M[id] = (\gamma, \sigma, S[\mathbf{while} \ r \ s], q) \qquad \sigma(r) \downarrow \mathbf{false}}{M \longrightarrow M[id := (\gamma, \sigma, S[\mathbf{skip}], q)]} \quad (\text{WHILE-DONE})$$

$$\frac{M[id] = (\gamma, \sigma, S[\mathbf{send}(r_1, e, r_2)], q)}{\sigma(r_1) \downarrow id' \qquad \sigma(r_2) \downarrow v \qquad M[id'] = (\gamma', \sigma', C', q')} \quad (\text{SEND})$$

$$\begin{split} M[id] &= ((n, \alpha) \cdot \gamma, \sigma, S[\mathbf{raise}\ (e, r)], q) \\ \sigma(r) \downarrow v \qquad \sigma' = \sigma[\mathbf{msg} := e][\mathbf{arg} := v] \qquad m = Name(id) \\ s &= \mathbf{if}\ Pop(m, n, \alpha, e) \lor Step(m, n, e) \neq \bot \\ \mathbf{then}\ Exit(m, n) \\ &= \mathbf{else\ skip} \\ \hline M \longrightarrow M[id := ((n, \alpha) \cdot \gamma, \sigma', s; \mathbf{raise}\ (e, v), q)] \\ \hline M \longrightarrow M[id := (\gamma, \sigma, S[\mathbf{leave}], q) \\ \overline{M \longrightarrow M[id := (\gamma, \sigma, \mathbf{skip}, q)]} (\text{LEAVE}) \\ \hline \frac{M[id] = (\gamma, \sigma, S[\mathbf{return}], q)}{M \longrightarrow M[id := (\gamma, \sigma, \mathbf{skip}, q)]} (\text{RETURN}) \\ \hline M[id] &= ((n, \alpha) \cdot \gamma, \sigma, \mathbf{skip}, q_1 \cdot (e, v) \cdot q_2) \qquad m = Name(id) \\ t = \{e \mid Trans(m, n, e) \neq \bot \lor Action(m, n, e) \neq \bot\} \\ d &= \{e \mid \alpha(e) = \top\} \qquad d' = (d \cup Deferred(m, n)) - t \\ |q_1| \subseteq d' \qquad e \notin d' \qquad \sigma' = \sigma[\mathbf{msg} := e][\mathbf{arg} := v] \\ s &= \quad \mathbf{if}\ Pop(m, n, \alpha, e) \lor Step(m, n, e) \neq \bot \\ \mathbf{then}\ Exit(m, n) \\ \hline M \longrightarrow M[id := ((n, \alpha) \cdot \gamma, \sigma', s; \mathbf{raise}\ (e, v), q_1 \cdot q_2)] \end{aligned}$$
(DEQUEUE

$$\begin{split} & M[id] = ((n, \alpha) \cdot \gamma, \sigma, \overline{\text{raise}}(e, v), q) \\ & m = Name(id) \qquad Step(m, n, e) = n' \\ \hline M \longrightarrow M[id := ((n', \alpha) \cdot \gamma, \sigma, Entry(m, n'), q)] \quad \text{(STEP)} \\ & M[id] = ((n, \alpha) \cdot \gamma, \sigma, \overline{\text{raise}}(e, v), q) \\ & m = Name(id) \qquad Trans(m, n, e) = \bot \\ & (\alpha(e) = a \wedge Action(m, n, e) = \bot) \vee Action(m, n, e) = a \\ & \underline{a \notin \{\bot, T\}} \\ \hline M \longrightarrow M[id := ((n, \alpha) \cdot \gamma, \sigma, Stmt(m, a), q)] \quad \text{(ACTION)} \\ & M[id] = ((n, \alpha) \cdot \gamma, \sigma, \overline{\text{raise}}(e, v), q) \\ & m = Name(id) \qquad Call(m, n, e) = n' \\ & \alpha' = \lambda e. \quad \text{if } (Trans(m, n, e) \neq \bot) \text{ then } \bot \\ & \text{ else if } (Action(m, n, e) \neq \bot) \text{ then } Action(m, n, e) \\ & \text{ else if } (e \in Deferred(m, n)) \text{ then } \top \\ & \text{ else } \alpha(e) \\ \hline M \longrightarrow M[id := ((n', \alpha') \cdot (n, \alpha) \cdot \gamma, \sigma, Entry(m, n'), q)] \quad \text{(CALL)} \\ & M[id] = ((n, \alpha) \cdot \gamma, \sigma, \overline{\text{raise}}(e, v), q) \\ & \frac{m = Name(id)}{M \longrightarrow M[id := (\gamma, \sigma, \text{raise}}(e, v), q)]} \text{ (PoP1) } \\ & \frac{M[id] = ((n, \alpha) \cdot \gamma, \sigma, \overline{\text{return}}, q) \quad m = Name(id) \\ & M[id] = ((n, \alpha) \cdot \gamma, \sigma, \overline{\text{return}}, q) \quad m = Name(id)} \\ & M[id] = ((n, \alpha) \cdot \gamma, \sigma, \overline{\text{return}}, q) \quad m = Name(id) \\ & M[id] = ((n, \alpha) \cdot \gamma, \sigma, \overline{\text{return}}, q) \quad m = Name(id) \\ & M \longrightarrow M[id := (\gamma, \sigma, \text{skip}, q)] \end{aligned}$$

$$\frac{M[id] = (\gamma, \sigma, S[\mathbf{assert}(r)], q) \qquad \sigma(r) \downarrow \mathbf{false}}{M \longrightarrow error} (ASSERT-FAIL)$$

$$\frac{M[id] = (\gamma, \sigma, S[\mathbf{send}(r_1, e, r_2)], q) \qquad \sigma(r_1) \downarrow \bot}{M \longrightarrow error} (SEND-FAIL1)$$

$$\frac{M[id] = (\gamma, \sigma, S[\mathbf{send}(r_1, e, r_2)], q)}{\sigma(r_1) \downarrow id' \qquad M[id'] = \bot} (SEND-FAIL2)$$

$$\frac{M[id] = (\epsilon, \sigma, s, q)}{M \longrightarrow error} (POP-FAIL)$$

Figure 6: Operational semantics: error transitions